

In case u_1, u_2, v_1, v_2 are all from \mathfrak{a}_1 or all from \mathfrak{a}_2 , then all contractions are zero so the brackets of two components from (3.22) or two from (3.23) are zero. If $u_1, v_1 \in \mathfrak{a}_1$ and $u_2, v_2 \in \mathfrak{a}_2$, then

$$\begin{aligned} & \left[\int_C :u_1(w)v_1(-w): w^k \frac{dw}{w}, \int_{C_1} :u_2(w_0)v_2(-w_0): w_0^l \frac{dw_0}{w_0} \right] \\ &= \int \left(\mp (-1)^{k+l} \{u_1, u_2\}_\pm :v_1(w_0)v_2(w_0): \right. \\ & \quad + i(-1)^k \{u_1, v_2\}_\pm :v_1(w_0)u_2(w_0): \\ & \quad + i(-1)^l \{v_1, u_2\}_\pm :u_1(w_0)v_2(w_0): \\ & \quad \mp \{v_1, v_2\}_\pm :u_1(w_0)u_2(w_0): w_0^{k+l} \\ & \quad \left. + k\delta_{k,-l} (\mp \{u_1, u_2\}_\pm \{v_1, v_2\}_\pm + i(-1)^k \{u_1, v_2\}_\pm \{v_1, u_2\}_\pm) \right). \quad (3.57) \end{aligned}$$

These calculations show that the components (all integral) of (3.21)–(3.23) with the identity operator form a closed Lie algebra acting on $V_\pm(Z')$.

To get the three extensions of this algebra we adjoin the components of (3.24)–(3.27) which include integral, semi-integral, or both kinds of components when $S = Z, Z'$, or $\frac{1}{2}Z$, respectively.

Let us define

$$\zeta = \begin{cases} (w-w_0)/2 & \text{if } S = Z, \\ (-ww_0)^{1/2} & \text{if } S = Z + \frac{1}{2} \end{cases}$$

and

$$\zeta' = \begin{cases} (w+w_0)/2 & \text{if } S = Z, \\ (ww_0)^{1/2} & \text{if } S = Z + \frac{1}{2}. \end{cases}$$

Also, let $\text{sgn}(Z) = 1$ and $\text{sgn}(Z + \frac{1}{2}) = -1$. From Lemma 8(a) we have

LEMMA 9. (a) For $|w| > |w_0|$, we have

$$\overline{e_S(w)e_S(w_0)} = \overline{e_S(-w)e_S(-w_0)} = \mp 2 \frac{\zeta}{w+w_0},$$

$$\overline{e_S(-w)e_S(w_0)} = \mp 2 \frac{\zeta'}{w-w_0},$$

$$\overline{e_S(w)e_S(-w_0)} = \mp 2 \text{sgn}(S) \frac{\zeta'}{w-w_0} \quad \text{for } S = Z, Z + \frac{1}{2},$$

$$\overline{e_{1/2Z}(w)e_{1/2Z}(-w_0)} = \overline{e_Z(-w)e_Z(w_0)} - \overline{e_{Z+1/2}(-w)e_{Z+1/2}(w_0)}.$$

(b) $S = Z$ or $Z + \frac{1}{2}$, $u \in \mathfrak{a}$, $|w| > |w_0|$, we have

$$\lim_{w \rightarrow w_0} \zeta = -w_0, \quad \lim_{w \rightarrow w_0} \zeta' = w_0,$$

$$\lim_{w \rightarrow w_0} :u(-w)e_S(-w_0): = :i:u(w_0)e_S(-w_0);$$

$$\lim_{w \rightarrow -w_0} :e_S(-w)e_S(-w_0): = \text{sgn}(S) :e_S(w_0)e_S(-w_0);$$

$$\lim_{w \rightarrow -w_0} :e_S(w)e_S(w_0): = :e_S(-w_0)e_S(w_0);$$

$$\lim_{w \rightarrow -w_0} :e_S(-w)e_S(-w_0): = \text{sgn}(S) :e_S(w_0)e_S(-w_0);$$

(c) For $S = Z$ or $Z + \frac{1}{2}$, $k \in Z$, we have

$$:e_S(w)e_S(-w):_k = (-1)^{-k} \text{sgn}(S) :e_S(-w)e_S(w):_k.$$

If $k \in Z + \frac{1}{2}$, we have

$$:e_Z(-w)e_Z(w):_k = i(-1)^k :e_Z(w)e_Z(-w):_k,$$

while for $k \in Z$ this is zero. For $S = \frac{1}{2}Z$, if $k \in Z$ we have

$$:e_S(-w)e_S(w):_k = :e_Z(-w)e_Z(w):_k + :e_Z(-w)e_Z(w):_k$$

and

$$:e_S(w)e_S(-w):_k = i(-1)^{-k} (:e_Z(-w)e_Z(w):_k - :e_Z(-w)e_Z(w):_k),$$

while if $k \in Z + \frac{1}{2}$, we have

$$:e_S(-w)e_S(w):_k = (1 - i(-1)^k) :e_Z(-w)e_Z(w):_k.$$

Let us begin with the case when $u_1, v \in \mathfrak{a}_1$ and $u_2 \in \mathfrak{a}_2$. We have

$$\begin{aligned} & \left[\int_{C_1} :u_1(w)u_2(w): w^k \frac{dw}{w}, \int_{C_2} :v(w_0)e_S(w_0): w_0^l \frac{dw_0}{w_0} \right] \\ &= \int_C \{u_2, v\}_\pm :u_1(w_0)e_S(w_0): w_0^{k+l} \frac{dw_0}{w_0}, \quad (3.58) \end{aligned}$$

while for $v \in \mathfrak{a}_2$, we have

$$\begin{aligned} & \left[\int_C :u_1(w) u_2(-w): w^k \frac{dw}{w}, \int_{C_1} :v(-w_0) e_S(w_0): w_0^k \frac{dw_0}{w_0} \right] \\ &= \int_C \mp \{u_1, v\}_\pm (-1)^k :u_2(-w_0) e_S(w_0): w_0^{k+r} \frac{dw_0}{w_0}. \end{aligned} \quad (3.59)$$

It is also clear from Lemma 8 that the brackets of components from (3.21)–(3.23) with components from (3.26)–(3.27) are all zero. The same is true for components of (3.22) with (3.24), and (3.23) with (3.25). If $u, v \in \mathfrak{a}_1$ and $u_2 \in \mathfrak{a}_2$, then

$$\begin{aligned} & \left[\int_C :u(w) v(-w): w^k \frac{dw}{w}, \int_{C_1} :u_2(-w_0) e_S(w_0): w_0^k \frac{dw_0}{w_0} \right] \\ &= \int_C (\{v, u_2\}_\pm :u(w_0) e_S(w_0): \\ & \mp \{u, u_2\}_\pm (-1)^k :v(w_0) e_S(w_0):) w_0^{k+r} \frac{dw_0}{w_0}; \end{aligned} \quad (3.60)$$

and if $u_1 \in \mathfrak{a}_1$, $u, v \in \mathfrak{a}_2$, then

$$\begin{aligned} & \left[\int_C :u(w) v(-w): w^k \frac{dw}{w}, \int_{C_1} :u_1(w_0) e_S(w_0): w_0^k \frac{dw_0}{w_0} \right] \\ &= \int_C (\mp \{u, u_1\}_\pm :v(-w_0) e_S(w_0): \\ & + \{v, u_1\}_\pm (-1)^k :u(-w_0) e_S(w_0):) w_0^{k+r} \frac{dw_0}{w_0}. \end{aligned} \quad (3.61)$$

That completes the brackets of components from (3.21)–(3.23) with those from (3.24)–(3.27).

Let $u, v \in \mathfrak{a}$; then Corollary 6 says that as expressions

$$\begin{aligned} & :u(w) e_S(w) v(w_0) e_S(w_0): \\ &= \pm \operatorname{sgn}(S) :v(w_0) e_S(w_0) u(w) e_S(w): \quad \text{for } S = \mathbb{Z} \text{ or } S = \mathbb{Z} + \frac{1}{2}. \end{aligned} \quad (3.62)$$

This determines whether we should commute (if $\pm \operatorname{sgn}(S) = 1$) or anticommute (if $\pm \operatorname{sgn}(S) = -1$) the components of $:u(w) e_S(w):$ and $:v(w_0) e_S(w_0):$. For $S = \frac{1}{2} \mathbb{Z}$, this depends on the components, that is, on k and l . But in all cases, we have

$$:u(w) e_Z(w) v(w_0) e_Z(w_0): = :v(w_0) e_Z(w_0) u(w) e_Z(w):. \quad (3.63)$$

So between components of $:u(w) e_Z(w):$ and $:v(w_0) e_Z(w_0):$, we always use the Lie bracket.

For $u, v \in \mathfrak{a}_1$ and $S = \mathbb{Z}$ or $\mathbb{Z} + \frac{1}{2}$, we have

$$\begin{aligned} & \left[\int_C :u(w) e_S(w): w^k \frac{dw}{w}, \int_{C_1} :v(w_0) e_S(w_0): w_0^l \frac{dw_0}{w_0} \right]_{\mp \operatorname{sgn}(S)} \\ &= \int_C \mp^S (\mp 2) (-1)^k :u(-w_0) v(w_0): w_0^{k+l} \frac{dw_0}{w_0}, \end{aligned} \quad (3.64)$$

where

$$\mp^S = \begin{cases} \mp 1 & \text{if } S = \mathbb{Z}, \\ +1 & \text{if } S = \mathbb{Z} + \frac{1}{2}. \end{cases}$$

For $u \in \mathfrak{a}_2$ and $S = \mathbb{Z}$ or $\mathbb{Z} + \frac{1}{2}$, we have

$$\begin{aligned} & \left[\int_C :u(-w) e_S(w): w^k \frac{dw}{w}, \int_{C_1} :v(-w_0) e_S(w_0): w_0^l \frac{dw_0}{w_0} \right]_{\mp \operatorname{sgn}(S)} \\ &= \int_C \mp^S (\mp 2) (-1)^k :u(w_0) v(-w_0): w_0^{k+l} \frac{dw_0}{w_0}. \end{aligned} \quad (3.65)$$

If $u \in \mathfrak{a}_1$, $v \in \mathfrak{a}_2$, $S = \mathbb{Z}$ or $\mathbb{Z} + \frac{1}{2}$, then

$$\begin{aligned} & \left[\int_C :u(w) e_S(w): w^k \frac{dw}{w}, \int_{C_1} :v(-w_0) e_S(w_0): w_0^l \frac{dw_0}{w_0} \right]_{\mp \operatorname{sgn}(S)} \\ &= \int_C (\mp^S \{u, v\}_\pm (-1)^k :e_S(-w_0) e_S(w_0): \\ & \mp^S (\mp 2) (-1)^k :u(-w_0) v(-w_0):) w_0^{k+l} \frac{dw_0}{w_0} \\ & \mp^S (\mp 2) \{u, v\}_\pm k (-1)^k \delta_{k,-l}. \end{aligned} \quad (3.66)$$

If $u_1 \in \mathfrak{a}_1$ and $S = \mathbb{Z}$ or $\mathbb{Z} + \frac{1}{2}$, we have the Lie bracket

$$\begin{aligned} & \left[\int_C :u_1(w) e_S(w): w^k \frac{dw}{w}, \int_{C_1} :e_S(-w_0) e_S(w_0): w_0^l \frac{dw_0}{w_0} \right] \\ &= \mp 2 \operatorname{sgn}(S) (1 - (-1)^{-l}) \int_C :u_1(w_0) e_S(w_0): w_0^{k+l} \frac{dw_0}{w_0}; \end{aligned} \quad (3.67)$$

while for $u_2 \in \mathfrak{a}_2$, we can see that

$$\begin{aligned} & \left[\int_C :u_2(-w) e_S(w): w^k \frac{dw}{w}, \int_{C_1} :e_S(-w_0) e_S(w_0): w_0^l \frac{dw_0}{w_0} \right] \\ &= \mp 2 \operatorname{sgn}(S) (1 - (-1)^{-l}) \int_C :u_2(-w_0) e_S(w_0): w_0^{k+l} \frac{dw_0}{w_0}. \end{aligned} \quad (3.68)$$

We must also compute for $S = \mathbb{Z}$ or $\mathbb{Z} + \frac{1}{2}$ the Lie bracket

$$\begin{aligned} & \left[\int_C :e_S(-w) e_S(w): w^k \frac{dw}{w}, \int_{C_1} :e_S(-w_0) e_S(w_0): w_0^k \frac{dw_0}{w_0} \right] \\ &= \mp 2 \operatorname{sgn}(S) (1 - (-1)^k) (1 + (-1)^{-k-t}) \\ & \quad \times \int_C :e_S(-w_0) e_S(w_0): w_0^{k+t} \frac{dw_0}{w_0} \\ & \quad + 4 \operatorname{sgn}(S) k (1 - (-1)^k) \delta_{k,-t}. \end{aligned} \quad (3.69)$$

The above calculations show that the extensions defined by (3.24)–(3.27) for $S = \mathbb{Z}$ and for $S = \mathbb{Z} + \frac{1}{2}$ give closed algebras. The case of $S = \frac{1}{2}\mathbb{Z}$ requires more work. Since $e_S(w) = e_Z(w) + e_{Z+1/2}(w)$, the calculations of brackets of components from (3.21)–(3.23) with those from (3.24)–(3.27) for $S = \mathbb{Z}$ and $S = \mathbb{Z} + \frac{1}{2}$ combine to give the same results for $S = \frac{1}{2}\mathbb{Z}$. In (3.64)–(3.66), if $k, t \in \mathbb{Z}$ or $k, t \in \mathbb{Z} + \frac{1}{2}$, the calculation is the same as for $S = \mathbb{Z}$ or $S = \mathbb{Z}'$, respectively. But if $k \in \mathbb{Z}$ and $t \in \mathbb{Z} + \frac{1}{2}$, the Lie bracket is used and gives zero for (3.64) and (3.65), because all contractions are zero.

Let $u \in \mathfrak{a}_1, v \in \mathfrak{a}_2, k \in \mathbb{Z}, t \in \mathbb{Z} + \frac{1}{2}$, then instead of (3.66) we have

$$\begin{aligned} & \left[\int_C :u(w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :v(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right] \\ &= \int_C \mp^Z \{u, v\}_\pm (-1)^k :e_Z(-w_0) e_Z(w_0): w_0^{k+t} \frac{dw_0}{w_0}. \end{aligned} \quad (3.70)$$

From Lemma 9(c) this is a linear combination of components from (3.26) and (3.27). If $k \in \mathbb{Z} + \frac{1}{2}$ and $t \in \mathbb{Z}$, we would have instead

$$\begin{aligned} & \left[\int_C :u(w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :v(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right] \\ &= \int_C \mp^Z \{u, v\}_\pm (-1)^{-t} :e_Z(-w_0) e_Z(w_0): w_0^{k+t} \frac{dw_0}{w_0}. \end{aligned} \quad (3.71)$$

Concerning the calculation (3.67), if $t \in \mathbb{Z}$, then we still use the Lie bracket whether $k \in \mathbb{Z}$ or $k \in \mathbb{Z} + \frac{1}{2}$. But the case when $k, t \in \mathbb{Z} + \frac{1}{2}$ reduces to

$$\begin{aligned} & \left[\int_C :u_1(w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :e_Z(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right]_{\pm} \\ &= \int_C \mp 2 (-1)^{-t} :u_1(w_0) e_Z(w_0): w_0^{k+t} \frac{dw_0}{w_0}, \end{aligned} \quad (3.72)$$

because as expressions, $:u_1(w) e_Z(w) e_Z(-w_0) e_Z(w_0):$ equals $\mp t :e_Z(-w_0) u_1(w) e_Z(w):$. If $k \in \mathbb{Z}$ and $t \in \mathbb{Z} + \frac{1}{2}$, then (3.67) reduces to

$$\begin{aligned} & \left[\int_C :u_1(w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :e_Z(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right]_{\mp} \\ &= \int_C \mp 2 t :u_1(w_0) e_Z(w_0): w_0^{k+t} \frac{dw_0}{w_0}, \end{aligned} \quad (3.73)$$

because as expressions, $:u_1(w) e_Z(w) e_Z(-w_0) e_Z(w_0):$ equals $\pm t :e_Z(-w_0) u_1(w) e_Z(w):$.

The case of calculation (3.68) is quite similar to that of (3.67). If $t \in \mathbb{Z}$, the Lie bracket is used whether $k \in \mathbb{Z}$ or $k \in \mathbb{Z} + \frac{1}{2}$, but the case when $k, t \in \mathbb{Z} + \frac{1}{2}$ reduces to

$$\begin{aligned} & \left[\int_C :u_2(-w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :e_Z(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right]_{\pm} \\ &= \int_C \mp 2 (-1)^{-t} :u_2(-w_0) e_Z(w_0): w_0^{k+t} \frac{dw_0}{w_0}, \end{aligned} \quad (3.74)$$

and the case when $k \in \mathbb{Z}, t \in \mathbb{Z} + \frac{1}{2}$ reduces to

$$\begin{aligned} & \left[\int_C :u_2(-w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :e_Z(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right]_{\mp} \\ &= \int_C \mp 2 t :u_2(-w_0) e_Z(w_0): w_0^{k+t} \frac{dw_0}{w_0}. \end{aligned} \quad (3.75)$$

The last calculation to be considered is (3.69). Lemma 9(c) shows that when $S = \frac{1}{2}\mathbb{Z}$ we are dealing with the components of $:e_Z(-w) e_Z(w):$, $:e_Z(-w) e_Z(w):$; and $:e_Z(-w) e_Z(w):$. The components of these first two are only integral, while the last are only semi-integral. The Lie brackets of the first two types with themselves have already been done in (3.69), and

$$\left[\int_C :e_Z(-w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :e_Z(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right] = 0, \quad (3.76)$$

because all contractions are zero. For $k \in \mathbb{Z}, t \in \mathbb{Z} + \frac{1}{2}$ we have Lie brackets

$$\begin{aligned} & \left[\int_C :e_Z(-w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :e_Z(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right] \\ &= \mp 2 t (1 - (-1)^k) \int_C :e_Z(-w_0) e_Z(w_0): w_0^{k+t} \frac{dw_0}{w_0} \end{aligned} \quad (3.77)$$

and

$$\begin{aligned} & \left[\int_C :e_Z(-w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :e_Z(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right] \\ &= \mp 2i(1 - (-1)^k) \int_C :e_Z(-w_0) e_Z(w_0): w_0^{k+t} \frac{dw_0}{w_0}. \end{aligned} \tag{3.78}$$

If $k, t \in \mathbb{Z} + \frac{1}{2}$ we have the anticommutator

$$\begin{aligned} & \left[\int_C :e_Z(-w) e_Z(w): w^k \frac{dw}{w}, \int_{C_1} :e_Z(-w_0) e_Z(w_0): w_0^t \frac{dw_0}{w_0} \right] + \\ &= \mp 2 \int_C ((-1)^{-t} :e_Z(-w_0) e_Z(w_0): \\ &+ (-1)^k :e_Z(-w_0) e_Z(w_0):) w_0^{k+t} \frac{dw_0}{w_0} + 4k(-1)^k \delta_{k,-t}. \end{aligned} \tag{3.79}$$

We have established our first main theorem.

THEOREM A. Let $Z = \mathbb{Z}$ or $\mathbb{Z} + \frac{1}{2}$, and let $A_{\pm}(Z^{2l})$ be the associative algebra with generators (3.2) and relations (3.3), and let $V_{\pm}(Z^l)$ be the representation space of $A_{\pm}(Z^{2l})$ generated by a vacuum vector v_0 (see paragraph containing (3.14)).

(a) For $S = Z, Z'$ or $\frac{1}{2}\mathbb{Z}$ we have the extension $A_{\pm}^S(Z^l)$ of $A_{\pm}(Z^l)$ obtained by adjoining the Clifford algebra generators (3.5), and we have the extension $V_{\pm}^S(Z^l)$ of $V_{\pm}(Z^l)$ obtained by tensoring with Clifford module $V(S)$.

Then the identity operator and the homogeneous components of generating functions $:u(w)v(w); u, v \in \mathfrak{a}$, represent a closed Lie algebra of operators on $V_{\pm}(Z^l)$. Each of the three extensions obtained by also including the components of $:u(w)e_S(w);$ and $:e_Z(w)e_Z(w):$ for $S = \frac{1}{2}\mathbb{Z}$, represents a closed algebra of operators on $V_{\pm}^S(Z^l)$.

(b) For $S = Z, Z'$, or $\frac{1}{2}\mathbb{Z}$ we have the extension $A_{\pm}^S(Z^l)$ of $A_{\pm}(Z^l)$ obtained by adjoining the Clifford, Weyl, or Clifford-Weyl algebra (3.52), and we have the extension $V_{\pm}^S(Z^l)$ of $V_{\pm}(Z^l)$ obtained by tensoring with appropriate module $V(S)$.

Then the identity operator and the homogeneous components of generating functions $:u_1(w)v_2(w); u_1(w)v_1(-w); u_2(w)v_2(-w); u_1, v_1 \in \mathfrak{a}_1, u_2, v_2 \in \mathfrak{a}_2$, represent a closed Lie algebra of operators on $V_{\pm}(Z^l)$. Each of the three extensions obtained by also including the components of $:u_1(w)e_S(w); u_2(-w)e_S(w); e_S(-w)e_S(-w);$ represents a closed algebra of operators on $V_{\pm}^S(Z^l)$.

4. IDENTIFICATION OF AFFINE ALGEBRAS

In this section we will review the root systems of the classical affine Kac-Moody algebras [6] and use the calculations of Section 3 to identify the algebras we have constructed.

The classical affine algebras will be organized into three series, the orthogonal series $D_l^{(1)}, B_l^{(1)}, D_{l+1}^{(2)}$, the symplectic series $C_l^{(1)}, B^{(1)}(0, l), C^{(2)}(l+1)$, and the general linear series $A_{2l-1}^{(2)}, A^{(2)}(0, 2l-1), A^{(4)}(0, 2l)$. There are for each of these algebras two natural gradations according to which endpoint of the Dynkin diagram corresponds to the affine simple root α_0 . This choice determines the finite-dimensional algebra \mathfrak{g} whose Dynkin diagram is that which remains when the affine point is removed. One way to obtain this grading and the corresponding root-space decomposition is to adjoin a derivation d to the affine algebra. This derivation acts as zero on the finite-dimensional algebra \mathfrak{g} , and acts as 1 or $\frac{1}{2}$ on the α_0 root-space determined by convenience.

TABLE VII

The Orthogonal Series

$\mathfrak{o}^{(1)}(2l)$ $D_l^{(1)}$		$\alpha_0 = \bar{d} - \epsilon_1 - \epsilon_2, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_{l-1} + \epsilon_l$ $\mathcal{A} = \{nd \pm (\epsilon_i \pm \epsilon_j), md \mid 1 \leq i, j \leq l, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$\mathfrak{o}^{(1)}(2l+1)$ $B_l^{(1)}$		$\alpha_0 = \bar{d} - \epsilon_1 - \epsilon_2, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\mathcal{A} = \{nd \pm \epsilon_i, nd \pm (\epsilon_i \pm \epsilon_j), md \mid 1 \leq i, j \leq l, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$\mathfrak{o}^{(2)}(2l+1)$ $B_l^{(2)} \approx B_l^{(1)}$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_{l-1} + \epsilon_l$ $\mathcal{A} = \{nd \pm (\epsilon_i \pm \epsilon_j), (n + \frac{1}{2})d \pm \epsilon_i, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$\mathfrak{o}^{(2)}(2l+2)$ $D_{l+1}^{(2)}$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\mathcal{A} = \{nd \pm (\epsilon_i \pm \epsilon_j), \frac{1}{2}nd \pm \epsilon_i, \frac{1}{2}md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$

TABLE VIII
The Symplectic Series

$sp^{(1)}(2l)$		$\alpha_0 = \bar{d} - 2\epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = 2\epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), nd \pm 2\epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$osp^{(1)}(1, 2l)$		$\alpha_0 = \bar{d} - 2\epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm \epsilon_1, nd \pm 2\epsilon_1, nd \pm (\epsilon_1 \pm \epsilon_j), md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$B^{(1)}(0, l)$		$\alpha_0 = \bar{d} - 2\epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm \epsilon_1, nd \pm 2\epsilon_1, nd \pm (\epsilon_1 \pm \epsilon_j), md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$osp^{(2)}(1, 2l)$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = 2\epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), nd \pm 2\epsilon_1, (n + \frac{1}{2})\bar{d} \pm \epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$B^{(2)}(0, l) \approx B^{(1)}(0, l)$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), nd \pm 2\epsilon_1, (n + \frac{1}{2})\bar{d} \pm \epsilon_1, \frac{1}{2}nd \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$osp^{(2)}(2, 2l)$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), nd \pm 2\epsilon_1, \frac{1}{2}nd \pm \epsilon_1, \frac{1}{2}md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$C^{(2)}(l+1)$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), nd \pm 2\epsilon_1, \frac{1}{2}nd \pm \epsilon_1, \frac{1}{2}md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$

Let $\{h_1, \dots, h_l\}$ be an orthonormal basis of the Cartan subalgebra \mathfrak{h} of \mathfrak{g} with respect to the invariant form as chosen in Section 2. The dual basis of \mathfrak{h}^* is denoted $\{\epsilon_1, \dots, \epsilon_l\}$. The Cartan subalgebra $\hat{\mathfrak{h}}$ of the extended affine algebra $\hat{\mathfrak{g}}$ will have basis $\{h_1, \dots, h_l, c, d\}$ such that

$$0 = \langle h_i, c \rangle = \langle h_i, d \rangle = \langle c, c \rangle = \langle d, d \rangle, \quad 1 = \langle c, d \rangle \quad (4.1)$$

with respect to the extended invariant form. We denote the dual basis of $\hat{\mathfrak{h}}^*$ by

$$\{\epsilon_1, \dots, \epsilon_l, \bar{c}, \bar{d}\}. \quad (4.2)$$

In Tables VII-IX, we give the simple roots, root system, and Dynkin diagram for the distinguishable gradations of the three series of classical affine algebras. An open circle in the Dynkin diagram indicates a super simple root. To assist in visualizing these root systems, we also give in Figs. 1-3 corresponding schematic root diagrams in which the super roots are indicated by an open circle.

The dimension of each root-space is one, except for the roots $m\bar{d}$, $0 \neq m \in \mathbb{Z}$, whose multiplicity is l . Note that the special linear series differs

TABLE IX. The General Linear Series

(a) $gl^{(2)}(2l)$		$\alpha_0 = \bar{d} - \epsilon_1 - \epsilon_2, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = 2\epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), 2nd \pm 2\epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$A_{2l-1}^{(2)}$		$\alpha_0 = \bar{d} - \epsilon_1 - \epsilon_2, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm \epsilon_1, nd \pm (\epsilon_1 \pm \epsilon_j), 2nd \pm 2\epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$gl^{(2)}(1, 2l)$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = 2\epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), 2nd \pm 2\epsilon_1, (n + \frac{1}{2})\bar{d} \pm \epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$A_{2l}^{(4)}$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), 2nd \pm 2\epsilon_1, \frac{1}{2}nd \pm \epsilon_1, \frac{1}{2}md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$gl^{(4)}(1, 2l+1)$		$\alpha_1 = \bar{d} - 2\epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_{l-1} + \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), (2n+1)\bar{d} \pm 2\epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
(b) $gl^{(2)}(2l)$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), (2n+1)\bar{d} \pm 2\epsilon_1, (n + \frac{1}{2})\bar{d} \pm \epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$A_{2l-1}^{(2)}$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_{l-1} + \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), (2n+1)\bar{d} \pm 2\epsilon_1, (n + \frac{1}{2})\bar{d} \pm \epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$gl^{(4)}(1, 2l)$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 \pm \epsilon_j), (2n+1)\bar{d} \pm 2\epsilon_1, (n + \frac{1}{2})\bar{d} \pm \epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$A_{2l}^{(2)}$		$\alpha_0 = \bar{d} - 2\epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm \epsilon_1, nd \pm (\epsilon_1 \pm \epsilon_j), (2n+1)\bar{d} \pm 2\epsilon_1, md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$gl^{(4)}(1, 2l+1)$		$\alpha_0 = \frac{1}{2}\bar{d} - \epsilon_1, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm \epsilon_1, nd \pm (\epsilon_1 \pm \epsilon_j), (2n+1)\bar{d} \pm 2\epsilon_1, \frac{1}{2}nd \pm \epsilon_1, \frac{1}{2}md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
(c) $gl^{(1)}(l)$		$\alpha_0 = \bar{d} - \epsilon_1 + \epsilon_l, \alpha_1 = \epsilon_1 - \epsilon_2, \dots, \alpha_{l-1} = \epsilon_{l-1} - \epsilon_l, \alpha_l = \epsilon_l$ $\Delta = \{nd \pm (\epsilon_1 - \epsilon_j), md \mid 1 \leq i, j \leq l, i < j, n \in \mathbb{Z}, 0 \neq m \in \mathbb{Z}\}$
$A_{l-1}^{(1)}$		

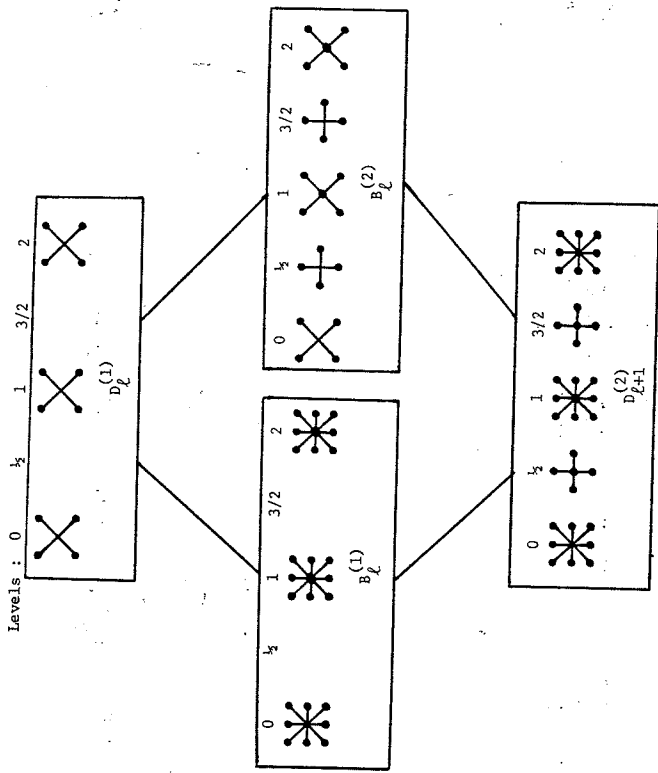


FIG. 1. The orthogonal series.

from our general linear series by having multiplicity $l-1$ in each $(2n+1)\bar{d}$ root-space, $n \in \mathbb{Z}$. Representations of the special linear series can be obtained from our general linear representations by taking the space of vacuum (highest weight) vectors for the infinite-dimensional Heisenberg algebra coming from the extra dimension in each $(2n+1)\bar{d}$ root-space.

Recall the bases which were chosen for the finite-dimensional algebras and the notation given at the end of Section 2 in formulas (2.5)-(2.10). The first type of construction we gave in Section 3 was based on the generating functions $:u(w)v(w);$ where $:uv \in \mathfrak{g}$ with $\mathfrak{g} = \mathfrak{o}(2l)$ in the fermionic case and $\mathfrak{g} = \mathfrak{sp}(2l)$ in the bosonic case. We then identify $h_i = \pm a_i a_i^*$; in the Cartan subalgebra \mathfrak{h} of \mathfrak{g} with

$$h_i(0) = \pm \int_C :a_i(w) a_i^*(w): \frac{dw}{w} \tag{4.3}$$

in the Cartan subalgebra \mathfrak{h} of the affine algebra $\hat{\mathfrak{g}}$. Then (3.34) shows that we have constructed a representation of $\mathfrak{o}^{(1)}(2l)$ in which central element c acts as $+1$ in the fermionic case, and a representation of $\mathfrak{sp}^{(1)}(2l)$ in which c acts as -1 in the bosonic case.

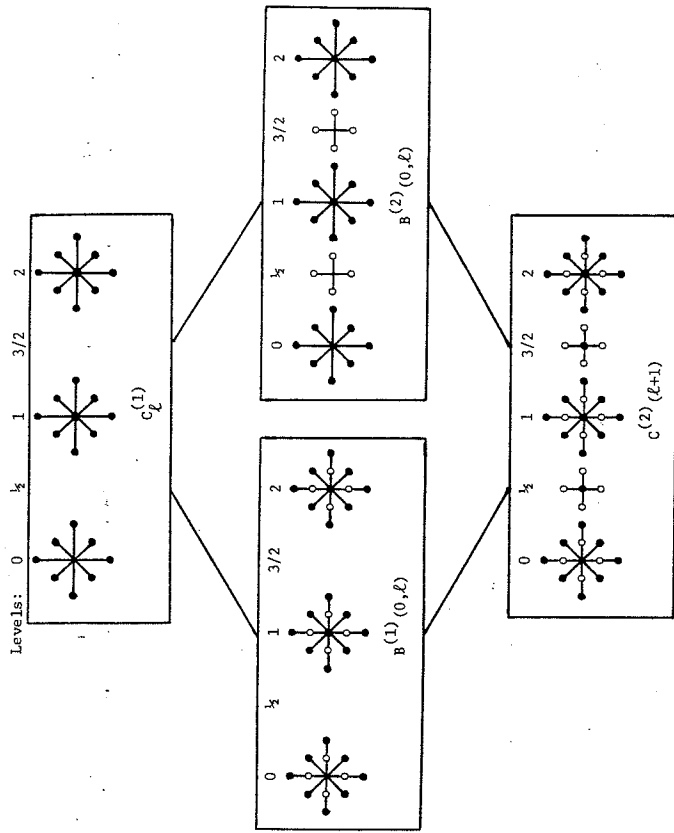


FIG. 2. The symplectic series.

The next construction we gave extended these algebras by allowing $:uv \in \mathfrak{g}$, where $\mathfrak{g} = \mathfrak{o}(2l+1)$ in the fermionic case and $\mathfrak{g} = \mathfrak{B}(0, l)$ in the bosonic case. For the new short root vectors $:ue$; the generating functions $:u(w)e_z(w)$; gave only integral components. Formulas (3.39) and (3.40) show that the resulting algebra is of type $B_l^{(1)}$ in the fermionic case and $B^{(1)}(0, l)$ in the bosonic case. If, instead, we use the functions $:u(w)e_z(w)$; so that short roots are only on the semi-integral levels, then (3.43) and (3.44) show that we obtained $B_l^{(2)}$ and $B^{(2)}(0, l)$. Finally, the largest extension of the series obtained by using $:u^{(w)}e_{1/2Z}(w)$; and $:e_z^{(w)}e_z(w)$; has the root system of $D_{l+1}^{(2)}$ in the fermionic case and that of $C^{(2)}(l+1)$ in the bosonic case. We have obtained purely fermionic constructions of the orthogonal series and purely bosonic constructions of the symplectic series. Note that since $\mathfrak{gl}^{(1)}(l)$ is contained in $\mathfrak{o}^{(1)}(2l)$, and $\mathfrak{sp}^{(1)}(2l)$ we have obtained both fermionic and bosonic constructions for type $A_{l-1}^{(1)}$. We will show in Section 5 that the restriction of these representations to $\mathfrak{gl}^{(1)}(l)$ has a simple decomposition into irreducible components.

The second type of construction we gave in Section 3 was based on the generating functions $:u_1(w)u_2(w); :u_1(w)v_1(-w); :u_2(w)v_2(-w);$ for