

Monday: Apr. 13: Math 304-6 Feingold / 1

Example: Try to diagonalize $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \in \mathbb{R}^3$.

Step ①: Find all possible e-values

$\lambda \in \mathbb{R}$ s.t. $AX = \lambda X$ for $0 \neq X \in \mathbb{R}^3$. $X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$

Suppose $AX = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \lambda \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ then it means

$$\begin{bmatrix} x_1 + x_2 + x_3 \\ x_1 + x_2 + x_3 \\ x_1 + x_2 + x_3 \end{bmatrix} = \begin{bmatrix} \lambda x_1 \\ \lambda x_2 \\ \lambda x_3 \end{bmatrix} = \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \lambda I_3 X$$

same as $(A - \lambda I_3)X = 0$ so looking for

$\lambda \in \mathbb{R}$ s.t. $\text{Nul}(A - \lambda I_3)$ is non-trivial

(*) has non-zero solutions.

$$2) [A - \lambda I_3 | 0^3] \Rightarrow \begin{bmatrix} 1-\lambda & 1 & 1 & | & 0 \\ 1 & 1-\lambda & 1 & | & 0 \\ 1 & 1 & 1-\lambda & | & 0 \\ -1 & -1 & \lambda-1 & & \end{bmatrix}$$

try row op's
 $-R_3 + R_1 \rightarrow R_1$
 $-R_3 + R_2 \rightarrow R_2$

get

$$\begin{bmatrix} -\lambda & 0 & \lambda & | & 0 \\ 0 & -\lambda & \lambda & | & 0 \\ 1 & 1 & 1-\lambda & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1-\lambda & | & 0 \\ \lambda & 0 & -\lambda & | & 0 \\ 0 & \lambda & -\lambda & | & 0 \end{bmatrix}$$

Two cases:
 $\lambda = 0$ or
 $\lambda \neq 0$

Case ① $\lambda = 0$: $\begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$ $\begin{matrix} x_1 = -r-s \\ x_2 = r \\ x_3 = s \end{matrix}$ free

$\lambda_1 = 0$

$\text{Nul}(A - \lambda I_3) = \text{Nul}(A) = A_0 = \left\{ \begin{bmatrix} -r-s \\ r \\ s \end{bmatrix} \in \mathbb{R}^3 \mid r, s \in \mathbb{R} \right\}$
 has basis $T_1 = \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$ $g_{\lambda_1} = \dim(A_{\lambda_1}) = 2$
 $w_{11} \quad w_{12}$

Check: $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = 0 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ 4

$A \quad w_{11} \quad = 0 w_{11}$

$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = 0 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$A \quad w_{12} \quad = 0 w_{12} \quad \quad \quad A \quad w_{21} \quad = 3 w_{21}$

$\begin{bmatrix} 1 & 0 & 0 & | & -1 & -1 & 1 \\ 0 & 1 & 0 & | & 1 & 0 & 1 \\ 0 & 0 & 1 & | & 0 & 1 & 1 \end{bmatrix}$ is in RREF so $S P_T = \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} = P$

$S \quad T \text{ (as columns)}$

$\begin{bmatrix} -1 & -1 & 1 & | & 1 & 0 & 0 \\ 1 & 0 & 1 & | & 0 & 1 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{matrix} + \\ + \end{matrix}} \begin{bmatrix} 1 & 0 & 1 & | & 0 & 1 & 0 \\ 0 & 1 & 1 & | & 0 & 0 & 1 \\ 0 & 0 & 3 & | & 1 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & | & -1/3 & 2/3 & -1/3 \\ 0 & 1 & 0 & | & -1/3 & -1/3 & 2/3 \\ 0 & 0 & 1 & | & 1/3 & 1/3 & 1/3 \end{bmatrix}$

$T \quad S$
(as columns)

$\frac{1}{3} \begin{bmatrix} -1 & 2 & -1 \\ -1 & -1 & 2 \\ 1 & 1 & 1 \end{bmatrix} T P_S = P^{-1}$

$$P^{-1}AP = \frac{1}{3} \begin{bmatrix} -1 & 2 & -1 \\ -1 & -1 & 2 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \quad \boxed{5}$$

$$= \frac{1}{3} \begin{bmatrix} -1 & 2 & -1 \\ -1 & -1 & 2 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & 3 \\ 0 & 0 & 3 \\ 0 & 0 & 3 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 9 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$= D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_2 \end{bmatrix} \text{ is diagonal, } \begin{array}{l} \lambda_1 = 0 \\ \lambda_2 = 3 \end{array}$$

Note: $\lambda_1 = 0$ was repeated corresponding to $g_{\lambda_1} = 2$.

Exercise: Show that $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ can not be diagonalized using only real numbers.

Th: Let $L: V \rightarrow V$ have distinct e-values 6

$\lambda_1, \dots, \lambda_r \in \mathbb{R}$ with corresponding e-vectors
 $w_1, \dots, w_r \in V$, so $L(w_i) = \lambda_i w_i$ for $1 \leq i \leq r$.

Then $S = \{w_1, \dots, w_r\} \subseteq V$ is independent.

Proof. Suppose $\theta = \sum_{i=1}^m c_i w_i$ is a shortest

dep. relation on S , so all $c_i \neq 0$, $1 \leq i \leq m$.

We may have relabeled vectors for convenience.

Apply L to get $\theta = \sum_{i=1}^m c_i L(w_i) = \sum_{i=1}^m c_i \lambda_i w_i$

Could also just multiply the dep rel. by λ_1 , get

$\theta = \sum_{i=1}^m c_i \lambda_1 w_i$. Subtract 2nd eq. from 1st:

Get $\theta = \sum_{i=1}^m c_i (\lambda_i - \lambda_1) w_i = \sum_{i=2}^m c_i (\lambda_i - \lambda_1) w_i$

Note: $m \geq 2$ since $\theta = c_1 \omega_1$ can't happen \square
($c_1 \neq 0, \omega_1 \neq \theta$).

The $i=1$ term is $c_1(\lambda_1, -\lambda_1)\omega_1 = c_1(0)\omega_1 = \theta$.
For $2 \leq i \leq m$, $\lambda_i - \lambda_1 \neq 0$ (distinct e-values),
so $\theta = \sum_{i=2}^m c_i(\lambda_i - \lambda_1)\omega_i$ is a shorter dep.
rel on S , contradicting "shortest" chosen. \square

Th: Let $L: V \rightarrow V$ have distinct e-values
 $\lambda_1, \dots, \lambda_r \in \mathbb{R}$ and for $1 \leq i \leq r$ let
 $T_i = \{\omega_{i1}, \dots, \omega_{ig_i}\}$ be a basis of e-space L_{λ_i} .
Then $T = T_1 \cup T_2 \cup \dots \cup T_r$ is independent.

Note: $T = \{\omega_{11}, \dots, \omega_{1g_1}, \omega_{21}, \dots, \omega_{2g_2}, \dots, \omega_{r1}, \dots, \omega_{rg_r}\}$
is a list of $g_1 + g_2 + \dots + g_r$ e-vectors in V .

Proof. Since $w_{ij} \in T_i \subseteq L_{\lambda_i}$ for $1 \leq i \leq r$ and $1 \leq j \leq g_i$ we have $L(w_{ij}) = \lambda_i w_{ij}$.

Suppose T were dependent, so there is a "shortest" dep. rel. on T . If necessary, by relabeling sets T_i and vectors in T_i , we could write that dep. rel. as

$$\theta = \sum_{i=1}^m \sum_{j=1}^{h_i} c_{ij} w_{ij} \quad \text{where each } c_{ij} \neq 0.$$
$$= \sum_{i=1}^m w_i \quad \text{where } w_i = \sum_{j=1}^{h_i} c_{ij} w_{ij} \in L_{\lambda_i}$$

and each $w_i \neq \theta$ since T_i is indep and $c_{ij} \neq 0$. But that contradicts the last Theorem, so T indep. \square

This means T is a basis of V iff $\lfloor 9$
 $g_1 + g_2 + \dots + g_r = n = \dim(V)$, so L is
diag-able iff we get a basis of e-vectors
for V , enough from each e-space L_{λ_i}
to make an e-basis for all of $V = \langle T \rangle$.

Focus now on finding all distinct e-values
 $\lambda_1, \dots, \lambda_r$ for $L: V \rightarrow V$ or for $A \in \mathbb{R}^n$.
Find all $\lambda \in \mathbb{R}$ s.t. $(L - \lambda I_V)(v) = \theta$
has solutions $v \neq \theta$, that is, s.t.
 $\ker(L - \lambda I_V) \neq \{\theta_V\}$. Let S be any basis
of V , and $A = {}_S[L]_S$ so $A - \lambda I_n = {}_S[L - \lambda I_V]_S$.

$\text{Nul}(A - \lambda I_n) \neq \{0\}$ iff $\text{rank}(A - \lambda I_n) < n$
iff $A - \lambda I_n$ is not invertible.
Use determinants to study this, and
for other uses.

Def. For $1 \leq n \in \mathbb{Z}$ (integer) let

$S = \{1, 2, \dots, n\}$ and let

$S_n = \text{Perm}(S) = \{f: S \rightarrow S \mid f \text{ is bijective}\}$

Notation: Write $f = \begin{pmatrix} 1 & 2 & \dots & i & \dots & n \\ f(1) & f(2) & \dots & f(i) & \dots & f(n) \end{pmatrix}$

like a table of values. Examples:

$S_2 = \left\{ \begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \right\}$ has only two elements.

$S_3 = \left\{ \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} \right\}$ has six elements.

For $f = (f^1(1) f^2(2) \dots f^n(n))$ there are 11
of choices: $n(n-1)\dots(2)(1) = n!$ ("n factorial")

So S_n contains $n!$ distinct elements, each
one a bijection from S to S .

Composition of any two elements of S_n
is another one, so have a binary operation
on S_n , \circ , composition.

Example: For $f = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$ and $g = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}$

find $f \circ g$ and $g \circ f$.

$$g = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}$$

$$f = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

$$f \circ g = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}$$

$$f = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

$$g = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}$$

$$g \circ f = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix}$$

Note:

$f \circ g \neq g \circ f$
can happen.

Note: $I = I_S = \begin{pmatrix} 1 & 2 & \dots & i & \dots & n \\ 1 & 2 & \dots & i & \dots & n \end{pmatrix}$ the identity [12]
map on S is bijective so $I \in S_n$ and
 $\forall f \in S_n, f \circ I = f = I \circ f$, so have an identity
element for \circ in S_n .

Also: $\forall f \in S_n, f^{-1} \in S_n$ since bijections are
invertible and their inverses are bijective.

Ex: $f = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 5 & 4 & 3 & 1 \end{pmatrix}$ has $f^{-1} = \begin{pmatrix} 2 & 5 & 4 & 3 & 1 \\ 1 & 2 & 3 & 4 & 5 \end{pmatrix}$

(just permute columns to
get top row in order) $= \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 5 & 1 & 4 & 3 & 2 \end{pmatrix}$

Th: (S_n, \circ, I) is a group under composition
with id. elt. I .

Def: For $f = (f(1) \dots f(i) \dots f(j) \dots f(n)) \in S_n$

Say f has an inversion for the pair (i, j) , $1 \leq i < j \leq n$, when $f(i) > f(j)$.

Ex: Inversions of $f = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \in S_3$
are marked below: (only one)

$f = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}$ has 3 inversions

Def: Let $\text{Inv}(f) = \text{Total number of inversions in } f \in S_n$.

Def: For $f \in S_n$ let $\text{sgn}(f) = (-1)^{\text{Inv}(f)} \in \{1, -1\}$ (say f is even or odd)

Def: For $A = [a_{ij}] \in \mathbb{R}^n$ define [14]

$$|A| = \det(A) = \sum_{\sigma \in S_n} \operatorname{sgn}(\sigma) a_{1\sigma(1)} a_{2\sigma(2)} \cdots a_{n\sigma(n)}$$

a sum ($n!$ terms) one term for each $\sigma \in S_n$
each term a product of n entries from
 A , one from each row, column number
depends on σ .

Ex: $n=2$: $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ $S_2 = \left\{ \begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \right\}$
 $\operatorname{sgn}(\sigma) = 1 \quad -1$

$$\det(A) = (+1)a_{11}a_{22} + (-1)a_{12}a_{21}$$

$$= a_{11}a_{22} - a_{12}a_{21}$$

"Cross hatching"

is usual 2×2
 $\det(A)$ formula.

EX: $n=3$: $A = [a_{ij}] \in \mathbb{R}_3^3$

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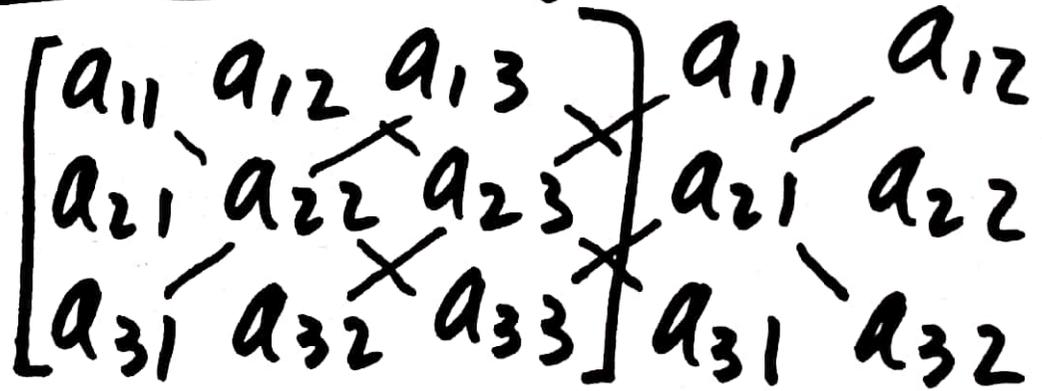
$S_3 = \left\{ \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix} \right\}$

sgn(σ): $\quad 1 \quad \quad -1 \quad \quad -1 \quad \quad +1 \quad \quad +1 \quad \quad -1$

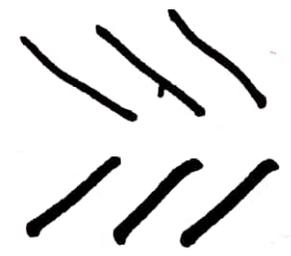
$\det(A) = 1 a_{11} a_{22} a_{33} + 1 a_{12} a_{23} a_{31} + 1 a_{13} a_{21} a_{32}$
 $- 1 a_{11} a_{23} a_{32} - 1 a_{12} a_{21} a_{33} - 1 a_{13} a_{22} a_{31}$

Crosshatching Method:

Warning:
 Crosshatching
 ONLY works
 for $n=2, 3$



Products of three "+1" terms
 Products of three "-1" terms



$$\underline{\text{Ex:}} \det \begin{bmatrix} 1 & -1 & 2 \\ 3 & 1 & -1 \\ 0 & 4 & 5 \end{bmatrix} \begin{matrix} 1 & -1 \\ 3 & 1 \\ 0 & 4 \end{matrix}$$

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$$= (1)(1)(5) + (-1)(-1)(0) + (2)(3)(4) - (2)(1)(0) - (1)(-1)(4) - (-1)(3)(5) = 5 + 24 + 4 + 15 = 48$$

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 3 & 1 & -1 \\ 0 & 4 & 5 \end{bmatrix} \xrightarrow{\text{adder}} \begin{bmatrix} 1 & -1 & 2 \\ 0 & 4 & -7 \\ 0 & 4 & 5 \end{bmatrix} \xrightarrow{\text{adder}} \begin{bmatrix} 1 & -1 & 2 \\ 0 & 4 & -7 \\ 0 & 0 & 12 \end{bmatrix}$$

$\begin{matrix} -3 & 3 & -6 \\ 0 & -4 & 7 \end{matrix}$
B

$$\det(B) = \begin{bmatrix} 1 & -1 & 2 \\ 0 & 4 & -7 \\ 0 & 0 & 12 \end{bmatrix} \begin{matrix} 1 & -1 \\ 0 & 4 \\ 0 & 0 \end{matrix} = (1)(4)(12) = 48$$

How do row operations affect $\det(A)$?

Facts about $\det(A)$.

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Th: Let $A = [a_{ij}] \in \mathbb{R}^n$. Then we have

- (a) If A has a row of zeros then $\det(A) = 0$
- (b) $\det(A^T) = \det(A)$
- (c) If A has two identical rows, then $\det A = 0$
- (d) If $\text{rank}(A) < n$ then $\det(A) = 0$
- (e) $\det(A) = 0$ implies $\text{rank}(A) < n$
- (f) $\det(A) = 0$ iff A is not invertible

Goal: Understand how elementary row operations affect $\det(A)$.