

More examples of Lie algebras:

11

Let V be a v.s. over \mathbb{F} and let $\langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{F}$ be a bilinear form on V . Let

$$\mathcal{L} = \{L: V \rightarrow V \mid \langle L(v_1), v_2 \rangle = -\langle v_1, L(v_2) \rangle, \forall v_1, v_2 \in V\}$$

Then $\mathcal{L} \leq \text{gl}(V)$ is a Lie subalgebra of $\text{gl}(V)$.

Pf. It is easy to check that \mathcal{L} is a subspace of $\text{gl}(V)$, so all we need to check is closure under commutator. Suppose $L_1, L_2 \in \mathcal{L}$, then

$$\begin{aligned}\langle [L_1, L_2](v_1), v_2 \rangle &= \langle (L_1 \circ L_2 - L_2 \circ L_1)(v_1), v_2 \rangle \\&= \langle L_1(L_2(v_1)), v_2 \rangle - \langle L_2(L_1(v_1)), v_2 \rangle \\&= \langle L_2(v_1), L_1(v_2) \rangle + \langle L_1(v_1), L_2(v_2) \rangle = \\&= \langle v_1, L_2(L_1(v_2)) \rangle - \langle v_1, L_1(L_2(v_2)) \rangle = -\langle v_1, [L_1, L_2](v_2) \rangle.\end{aligned}$$

Let's view \mathcal{L} from the matrix point of view. [12]

Let V have basis $S = \{v_1, \dots, v_n\}$ and let
 $M_S = [\langle v_i, v_j \rangle]$ be the $n \times n$ matrix of the
bilinear form w.r.t. S . Using notation

$[v]_S = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \in F^n$ when $v = \sum_{j=1}^n a_j \cdot v_j$ for the

coordinates of $v \in V$ w.r.t. S , we have

$$\langle v, w \rangle = [v]_S^{Tr} M_S [w]_S \quad \text{if } a \text{ } 1 \times 1 \text{ matrix}$$

$1 \times n \quad n \times n \quad n \times 1$

is just a scalar.

$\forall v, w \in V$

Note: If $[w]_S = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$ then both sides of the above

$$\sum_{i=1}^n \sum_{j=1}^n a_i b_j \langle v_i, v_j \rangle.$$

For $L: V \rightarrow V$ we use the notation $A = \underline{L}$

$[L]_S \in F_n^n$ for the matrix representing L with respect to S , so $\forall v \in V$ we have

$$[L]_S [v]_S = [L(v)]_S .$$

$$\begin{array}{ccc} V & \xrightarrow{\underline{L}} & V \\ \downarrow [L]_S & & \downarrow [L]_S \end{array}$$

Then $L \in \mathcal{L}$ means, $\forall v, w \in V$, $F^n \xrightarrow[n \times n]{s[L]_S} F^n$

$$\langle L(v), w \rangle = -\langle v, L(w) \rangle \text{ iff}$$

$$[L(v)]_S^T M_S [w]_S = -[v]_S^T M_S [L(w)]_S \text{ iff}$$

$$(A[v]_S)^T M_S [w]_S = -[v]_S^T M_S (A[w]_S) \text{ iff}$$

$$[v]_S^T (A^T M_S) [w]_S = -[v]_S^T (M_S A) [w]_S$$

Since this is true $\forall v, w \in V$, it is true [14]

$\forall X = [v]_S, Y = [w]_S \in F^n$, that is,

$$X^T (A^T {}_S M_S) Y = -X^T (-S M_S A) Y.$$

Using $v = v_i \in S, w = v_j \in S$, we get

$X = e_i, Y = e_j$ standard basis vectors in F^n
and $e_i^T B e_j = b_{ij}$. for any $B = [b_{ij}] \in F^n$,

so the (i, j) th entries of $A^T {}_S M_S$ and $-S M_S A$
are equal for all $1 \leq i, j \leq n$, so

$A^T {}_S M_S = -S M_S A$ is the condition on
 $A = [L]_S$, equivalent to $L \in \mathcal{L}$.

Th: For any $n \times n$ matrix $M \in F_n^n$, Let 15
 $\mathcal{L}(M) = \{A \in F_n^n \mid A^T M = -MA\}$. Then
 $\mathcal{L}(M)$ is a Lie subalgebra of $gl(n, F)$.

The most important special cases are:
① $\langle v, w \rangle = \langle w, v \rangle$ symmetric bilinear form
(non-degenerate)
② $\langle v, w \rangle = -\langle w, v \rangle$ antisymmetric bil. form
(non-deg.) $\Rightarrow \dim(V)$ is even

Corresponding to

- ① $M = M^T$ sym. non-deg. matrix
- ② $M = -M^T$ antisym. non-deg. matrix (n even)

Call the corresponding Lie algebra

"orthogonal" in case ①, "symplectic" in case ②.

Ex: $M = I_n = M^{\text{Tr}}$ gives

[16]

$$\mathcal{L}(M) = \mathcal{L}(I_n) = \{AEF_n^n \mid A^{\text{Tr}} = -A\}.$$

In textbook (Humphreys), for a more uniform presentation, he used M in block form:

$$\textcircled{1} \quad M = \begin{bmatrix} O & I_e \\ I_e & O \end{bmatrix} \in F_{2e}^{2e}, \quad n=2e \text{ even: } \boxed{o(2e, F)}$$

$$\textcircled{1}' \quad M = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & I_e \\ 0 & I_e & 0 \end{bmatrix} \in F_{2e+1}^{2e+1}, \quad n=2e+1 \text{ odd: } \boxed{o(2e+1, F)}$$

$$\textcircled{2} \quad M = \begin{bmatrix} O & I_e \\ -I_e & O \end{bmatrix} \in F_{2e}^{2e}, \quad n=2e: \boxed{sp(2e, F)}$$

while $sl(e+1, F)$ is called "Type A_e ".

Using block forms for $A \in \mathcal{L}$ in each case / 17
 we can get precise conditions on each block
 from $A^T M = -MA$ giving an explicit basis
 for each type of "classical matrix Lie alg."
 in these four series of Lie algebras.

$$\text{Get } \dim(\mathfrak{o}(2l, F)) = 2l^2 - l$$

$$\dim(\mathfrak{o}(2l+1, F)) = 2l^2 + l$$

$$\dim(\mathfrak{sp}(2l, F)) = 2l^2 + l$$

$$\dim(\mathfrak{sl}(l+1, F)) = (l+1)^2 - 1$$

Other important Lie subalgebras of $\mathfrak{gl}(n, F)$:

$$t(n, F) = \{ A = [a_{ij}] \in F_n^n \mid a_{ij} = 0 \text{ if } i > j \} \text{ (upper } \Delta \text{)}$$

$$n(n, F) = \{ A = [a_{ij}] \in F_n^n \mid a_{ij} = 0 \text{ if } i \geq j \} \text{ (strictly upper } \Delta \text{)}$$

$$d(n, F) = \{ \dots \dots \dots \mid a_{ij} = 0 \text{ if } i \neq j \} \text{ (diagonal)}$$

Facts: $t(n, F) = d(n, F) \oplus n(n, F)$ is a direct sum as vector spaces. Let $t = t(n, F)$.
 $[d(n, F), d(n, F)] = 0$ so $d = d(n, F)$ is abelian.
 $[d, t] \subseteq t$ and actually, $[d, t] = n$.

For $0 \leq k$ let $t_k = \bigoplus_{i=1}^n F E_{i(i+k)}$ so

$$t_0 = \left\{ \begin{bmatrix} a_{11} & & 0 \\ & \ddots & \\ 0 & & a_{nn} \end{bmatrix} \right\} = d, \quad t_1 = \left\{ \begin{bmatrix} 0 & a_{12} & & & 0 \\ 0 & a_{23} & & & \\ 0 & 0 & \ddots & & \\ 0 & 0 & \cdots & a_{(n-1)n} & 0 \end{bmatrix} \right\}$$

$$t_2 = \left\{ \begin{bmatrix} 0 & 0 & a_{13} & 0 \\ 0 & 0 & a_{24} & \\ \ddots & \ddots & \ddots & \\ 0 & 0 & \cdots & 0 \end{bmatrix} \right\}, \dots, t_{n-1} = \left\{ \begin{bmatrix} 0 & 0 & \cdots & 0 & a_{1n} \\ 0 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 0 \end{bmatrix} \right\}$$

Check: $[t_i, t_j] \subseteq t_{i+j}$ as subspaces, since

$$[E_{r(r+i)}, E_{s(s+j)}] = \delta_{(r+i), s} E_{r(s+j)} - \underline{\delta_{(s+j), r} E_{s(r+i)}}$$

$$= \delta_{(r+i), s} E_{r(r+i+j)} - \delta_{(s+j), r} E_{s(s+i+j)}.$$

For $\mathbb{R} \ni n$, $t_k = \{0_n\}$.

Def. A Lie algebra L is " \mathbb{Z} -graded" when $\forall k \in \mathbb{Z}$, there is a subspace L_k of L s.t.

$$[L_k, L_m] \subseteq L_{k+m} \quad \forall k, m \in \mathbb{Z}, \text{ and}$$

$L = \bigoplus_{k \in \mathbb{Z}} L_k$ is a direct sum of subspaces.

Can have some $L_k = \{0\}$. Can be generalized.

Examples of representations:

(20)

For $L = \text{gl}(n, F)$, define a rep'n of L on $V = F^n$ (column vectors) by left matrix multiplication; $\phi: L \rightarrow \text{End}(F^n)$ is

$$\phi(A)(X) = AX, \quad \forall A \in F_n^n, X \in F^n. \text{ Then}$$

$$\phi([A, B])(X) = (A \circ B - B \circ A)X = A(BX) - B(AX)$$

$$= \phi(A)(\phi(B)(X)) - \phi(B)(\phi(A)(X))$$

$$= (\phi(A)\phi(B) - \phi(B)\phi(A))X = (AB - BA)X$$

$$= [\phi(A), \phi(B)](X) \quad \text{so } \phi \text{ is a Lie alg. rep'n.}$$

If $L \leq gl(n, F)$ is any Lie subalgebra [2] of $gl(n, F)$, we get a rep'n of L on F^n by the same "action", left matrix mult.

Explicit case: $L = sl(2, F)$ rep'd on F^2 .
 Let $S = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} = v_1, \begin{bmatrix} 0 \\ 1 \end{bmatrix} = v_2 \right\}$ be std. basis of F^2 .

L has basis: $e = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, f = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, h = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$.

Check: $ev_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, fv_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = v_2, hv_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = v_1$

and $ev_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = v_1, fv_2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, hv_2 = \begin{bmatrix} 0 \\ -1 \end{bmatrix} = -v_2$

so action of h on $V = F^2$ is diagonal with e-values 1 (on Fv_1), -1 (on Fv_2).

Example: Let $V = \mathbb{F}[x, y]$ v.s. over \mathbb{F} of [22] polynomials in two variables. Define operators

$E = x\partial_y$, $F = y\partial_x$, $H = x\partial_x - y\partial_y$ where ∂_x and ∂_y are partial derivatives w.r.t. x and y , respectively. For monomials, $x^i y^j$, we have: $(x\partial_y) x^i y^j = j x^{i+1} y^{j-1}$

$$(y\partial_x) x^i y^j = i x^{i-1} y^{j+1} \quad \text{so}$$

$$\begin{aligned} [E, F] x^i y^j &= ((x\partial_y) \circ (y\partial_x) - (y\partial_x) \circ (x\partial_y)) x^i y^j \\ &= i(j+1) x^i y^j - j(i+1) x^i y^j = (i-j) x^i y^j \\ &= (x\partial_x - y\partial_y) x^i y^j = H x^i y^j. \end{aligned}$$

So as linear operators on V , we have $[E, F] = H$.

Exercise: Using the formulas above for [23]
 the actions of these linear operators on V ,
 check that $[H, E] = 2E$ and $[H, F] = -2F$.

Hint: Apply to monomial $x^i y^j$.

Th: The linear map $\phi: \text{sl}(2, F) \rightarrow \text{End}(F[x, y])$
 such that $\phi(e) = E = x\partial_y$, $\phi(f) = F = y\partial_x$
 and $\phi(h) = H = x\partial_x - y\partial_y$, is a Lie alg. rep'n.

Def. For $\phi: L \rightarrow \text{End}(V)$ a rep'n, we say V
 is an "L-module" where "L acts on V " by
 $x \cdot v = \phi(x)(v)$, $\forall x \in L, \forall v \in V$. So $\cdot: L \times V \rightarrow V$ is
 Just an equivalent terminology with simpler
 notation: $[x, y] \cdot v = x \cdot (y \cdot v) - y \cdot (x \cdot v)$.

Def. Let V be an L -module and $W \leq V$ a subspace. Say W is a sub-module of V when $\forall x \in L, \forall w \in W, x \cdot w \in W$, that is, W is itself an L -module. This is the same as saying that rep'n $\phi: L \rightarrow \text{End}(V)$ has a restriction $\phi_W: L \rightarrow \text{End}(W)$ by $\phi_W(x) = \phi(x)|_W: W \rightarrow W$.

Example: In the previous example where $L = M(2, F)$ and $V = F[x, y]$, for $0 \leq m \in \mathbb{Z}$ let $V_m = F\text{-span} \{x^m, x^{m-1}y, x^{m-2}y^2, \dots, xy^{m-1}, y^m\}$ $= F\text{-span} \{x^i y^j \mid i+j=m\}$ be the subspace of all polynomials in V of homogeneous degree m .

Th: For each $0 \leq m \in \mathbb{Z}$ the subspace 125
 V_m in V is an L -submodule with $\dim(V_m) = m+1$.
Pf. The formulas for the action of E, F, H on
monomials $x^i y^j$ show that the homog. degree
 $i+j$ is preserved by their action. \square

Note: The action of H on $x^i y^j$ is mult by $i-j$
so H is diagonal with eigenvalues:
 $m, m-2, m-4, \dots, -(m-2), -m$
and these match the "natural" rep'n on \mathbb{F}^2
for $m=1$.
The "trivial" rep'n for $m=0$ is 1-dim'l with
all operators acting as zero.

Example: Let $V = F[X]$, and let $p = \partial_x$ be 26 differentiation w.r.t. x , $q = x$ be mult. by x . Then $[p, q] x^i = (\partial_x x - x \partial_x) x^i = (i+1)x^{i+1} - ix^i = 1x^i$ so $[p, q] = I$ is the identity operator on V .

of course, $[I, p] = 0 = [I, q]$ so the three operators p, q, I span a 3-dim'l Lie alg. inside $gl(V)$, called a Heisenberg Lie alg., \underline{h}

Note: $[\underline{h}, \underline{h}] = FI = \underline{h}'$ so $[\underline{h}', \underline{h}] = 0$ and $[\underline{h}, [\underline{h}, \underline{h}]] = 0$. \underline{h} is used in physics as a model of position, momentum, uncertainty principle.