

$$X = X_{\Sigma}$$

$$\text{ray } \mathcal{R}_{\Sigma}$$

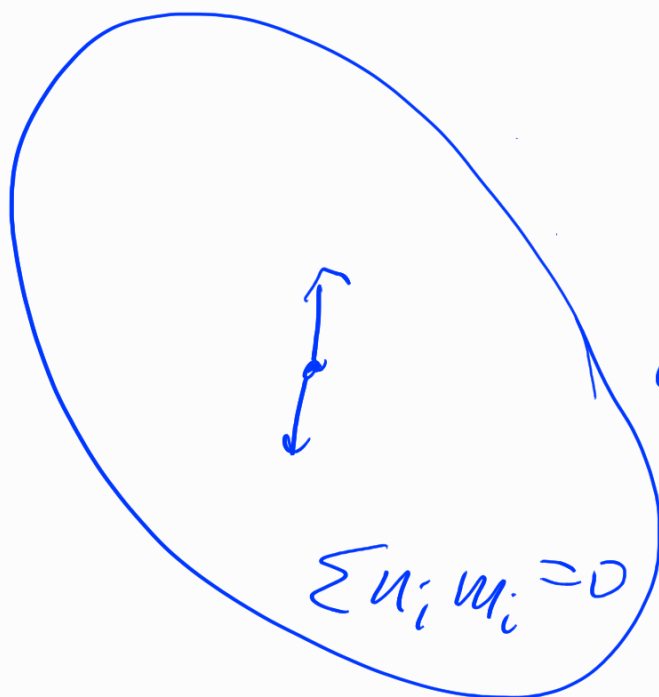
$$R_i = \langle n_1, n_2, \dots, n_d \rangle \quad N$$

$$\gcd(n_1, n_2, \dots, n_d) = 1$$

$$\omega = \frac{dx_1}{x_1} \wedge \frac{dx_2}{x_2} \wedge \dots \wedge \frac{dx_d}{x_d}$$

$$F_i = X_{R_i} \setminus (\mathbb{C}^*)^d$$

$$\hat{R}_i = \{(m_1, m_2, \dots, m_d) \mid \sum_{i=1}^d n_i m_i \geq 0\}$$



$$\text{cospa}(\hat{R}_i)$$

$$\text{span}(R_i)$$

$M \cap \text{Cospan}(\hat{R}_i)$ is generated
as a group by

$$y_1, \dots, y_{d-1}$$

as a subgroup:

$$y_1, y_2, \dots, y_{d-1}, y_1^{-1}, \dots, y_{d-1}^{-1}$$

Take $y_d = (m_1, \dots, m_d)$

$$\text{s.t. } n_1 m_1 + \dots + n_d m_d = 1$$

$$\hat{R}_i \cap M = \langle y_1^{\pm 1}, \dots, y_{d-1}^{\pm 1}, y_d \rangle$$

$$M = \langle y_1^{\pm 1}, \dots, y_{d-1}^{\pm 1}, y_d^{\pm 1} \rangle$$

At a generic point

of E_i

$y_1, \dots, y_d$ are the
local coordinates

$$\text{and } E_i = \{y_d = 0\}$$

$$y_k = \prod_{j=1}^d x_j^{a_{jk}} \quad a_{jk} \in \mathbb{Z}$$

$$\det(a_{jk}) = \pm 1$$

Lemma. $\frac{dx_1}{x_1} \wedge \dots \wedge \frac{dx_d}{x_d}$

$$= (\pm 1) \cdot \frac{dy_1}{y_1} \wedge \dots \wedge \frac{dy_d}{y_d}$$

$$\begin{pmatrix} \log y_1 \\ \vdots \\ \log y_d \end{pmatrix} = (a_{jk}) \begin{pmatrix} \log x_1 \\ \vdots \\ \log x_d \end{pmatrix}$$

Ex. $d=2$

$$\begin{cases} y_1 = x_1^2 x_2^1 \\ y_2 = x_1^3 x_2^1 \end{cases} \quad \begin{cases} x_1 = y_1^{-1} y_2 \\ x_2 = y_1^3 y_2^{-2} \end{cases}$$

$$\begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} -1 & 1 \\ 3 & -2 \end{pmatrix}$$

$$\begin{cases} \log x_1 = -\log y_1 + \log y_2 \\ \log x_2 = 3\log y_1 - 2\log y_2 \end{cases}$$

$$\begin{cases} \frac{dx_1}{x_1} = -\frac{dy_1}{y_1} + \frac{dy_2}{y_2} \\ \frac{dx_2}{x_2} = 3\frac{dy_1}{y_1} - 2\frac{dy_2}{y_2} \end{cases}$$

$$\begin{bmatrix} \frac{dx_1}{x_1} \\ \frac{dx_2}{x_2} \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 3 & -2 \end{bmatrix} \begin{bmatrix} \frac{dy_1}{y_1} \\ \frac{dy_2}{y_2} \end{bmatrix}$$

$$\frac{dx_1}{x_1} \wedge \frac{dx_2}{x_2} = \det \begin{pmatrix} -1 & 1 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} \frac{dy_1}{y_1} \wedge \frac{dy_2}{y_2} \end{pmatrix}$$

" -1

$$\omega = (\pm 1) \frac{dy_1}{y_1} \wedge \dots \wedge \frac{dy_d}{y_d}$$

$$= \pm \frac{1}{y_1 \dots y_{d-1}} \cdot \left(\frac{1}{y_d} \right) dy_1 \wedge \dots \wedge dy_d$$

unit at a generic point
on E_i $E_i = \{y_d = 0\}$
 ω has a pole of order
1 at E_i . □

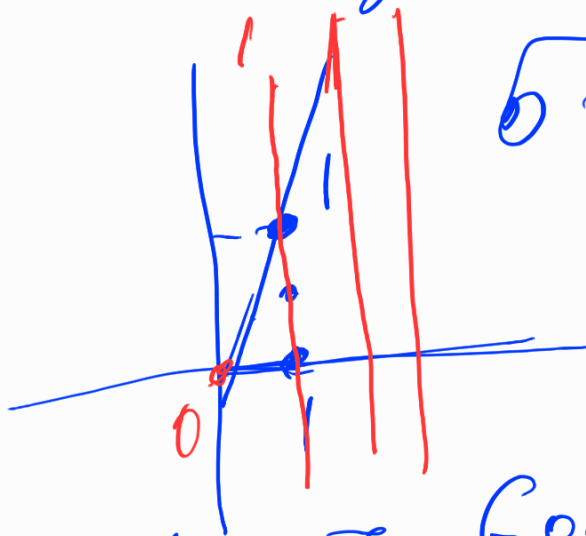
Def. X is Gorenstein
if K_X is Cartier

Def. X is $\mathbb{Q}$ -Gorenstein
if nK_X is Cartier for some $n \neq 0$.

Combinatorially:

Thm. X_Σ is Gorenstein
 if $\forall$ cone $\sigma \in \Sigma$
 the rational linear
function on $N \cap \text{span}(\sigma)$
 that takes value 1
 at the closest points
 of the rays is integer

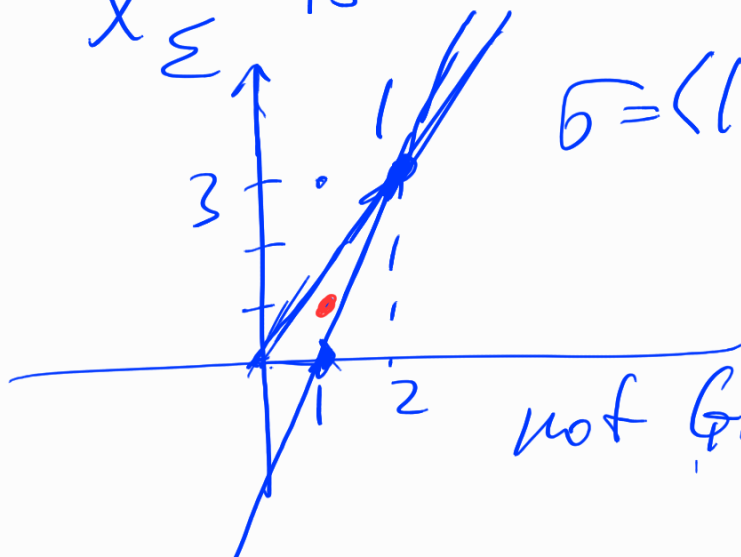
Ex.



$$\sigma = \langle (1,0), (1,2) \rangle$$

Thus X_Σ is Gorenstein

Ex.



$$\sigma = \langle (1,0), (2,3) \rangle$$

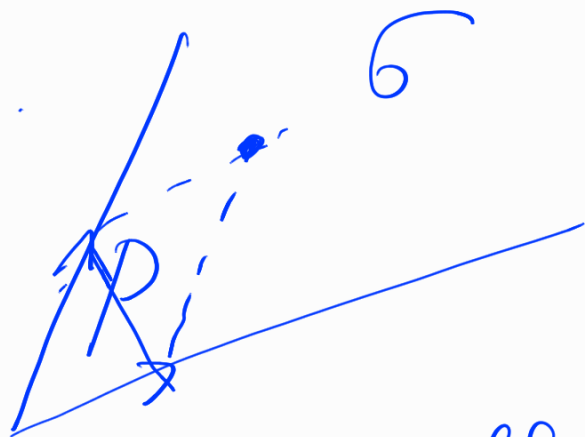
not Gorenstein

The linear function

$$\mapsto (u_1, u_2) \mapsto m_1 u_1 + m_2 u_2$$

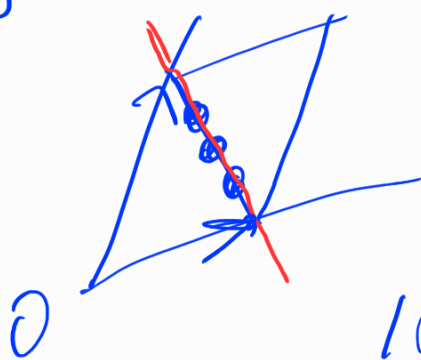
$$\begin{cases} m_1 = 1 \\ 2m_1 + 3m_2 = 1 \end{cases} \quad \begin{matrix} m_1 = 1 \\ m_2 = -\frac{1}{3} \notin \mathbb{Z} \end{matrix}$$

In dim 2.



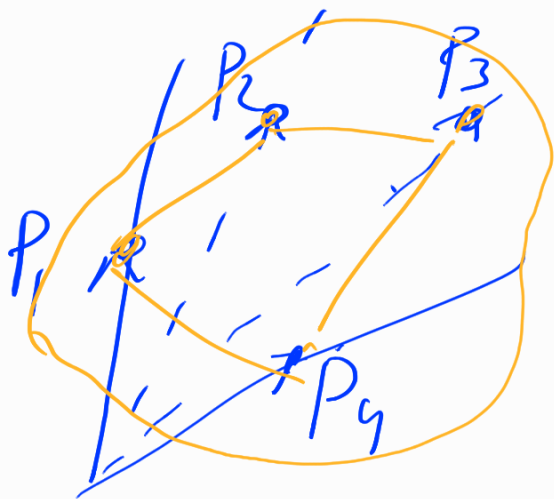
X_6 is smooth iff P has no integer points ($\mathbb{Z}N$) except for vertices.

X_6 is Gorenstein iff all points are vertices or



are on this line, conic rays

What if this rational
linear function does not
exist? $\dim = 3$



If all P_i are on
one hyperplane, then
this linear function exists.

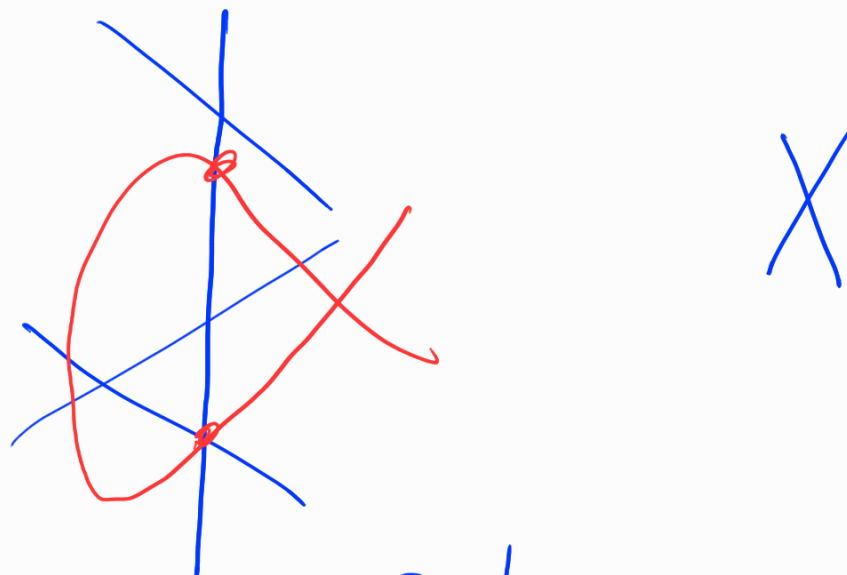
In this case X_6

is $\mathbb{Q}$ -Gorenstein.

smooth $\subset$ Gorenstein

$\cap$
 $\mathbb{Q}$ -Gorenstein

Blow-up of a point

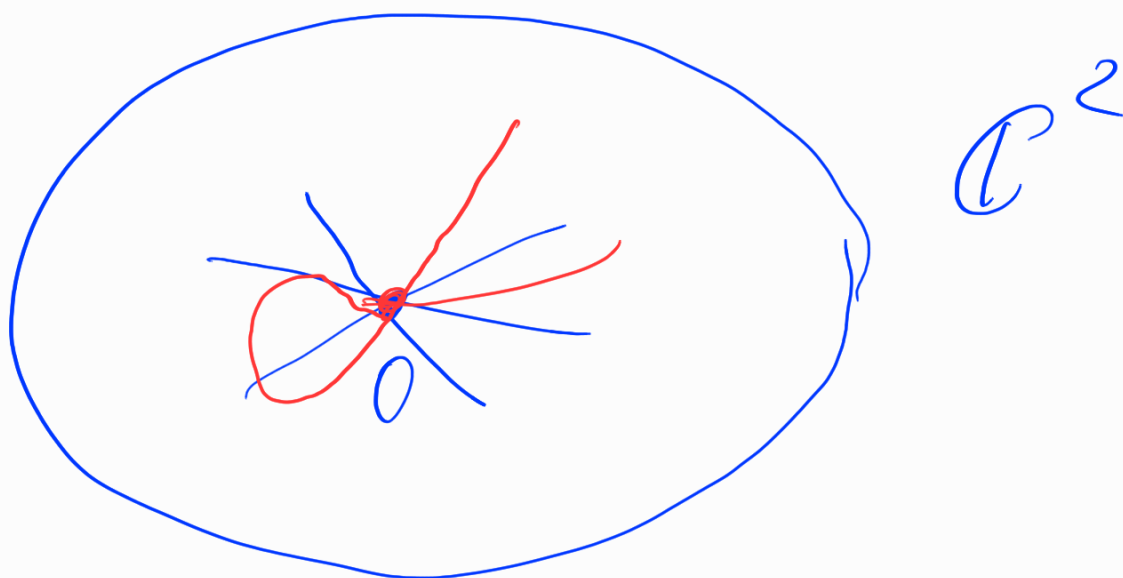


$$E \cong \mathbb{CP}^1$$

$$X \setminus E \cong \mathbb{C}^2 \setminus \{0\}$$



$$\pi(E) = 0$$

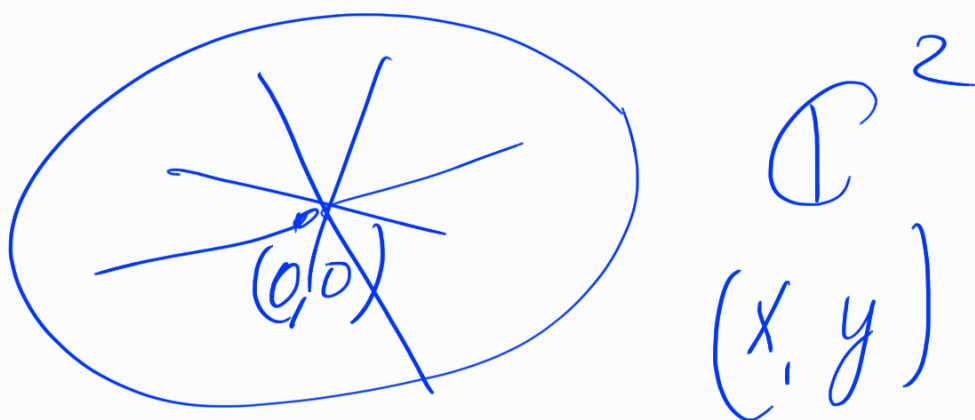


$$X \subseteq \mathbb{C}^2 \times \mathbb{CP}^1$$

$$(x, y), (s:t)$$

$$X = \{xt = ys\}$$

$\pi \downarrow$ $\downarrow$ projection to $\mathbb{C}^2$



If $(x, y) = (0, 0)$

$$\forall (s:t) \quad \underset{0}{x}t = \underset{0}{y}s$$

If $(x, y) \neq (0, 0)$ on $\mathbb{CP}^1$

$$\text{then } xt = ys \Leftrightarrow (x:y) = (s:t)$$

$$\forall (s:t) \in \mathbb{CP}^1$$

$$\{(x, y), (s:t) \mid xt = ys\}$$

$$(x, y) = \lambda \cdot (s, t)$$

$$\lambda \in \mathbb{C}$$

X is smooth,

X is a union of two

$\mathbb{C}^2$:

$$\mathbb{CP}^1 = \{t \neq 0\} \cup \{s \neq 0\}$$

$$X \cap \{t \neq 0\} \quad \left(z = \frac{s}{t} \right)$$

$$(x, y), (s:t) \quad \frac{xt = ys}{}$$

$$\left(x = yz \right)$$

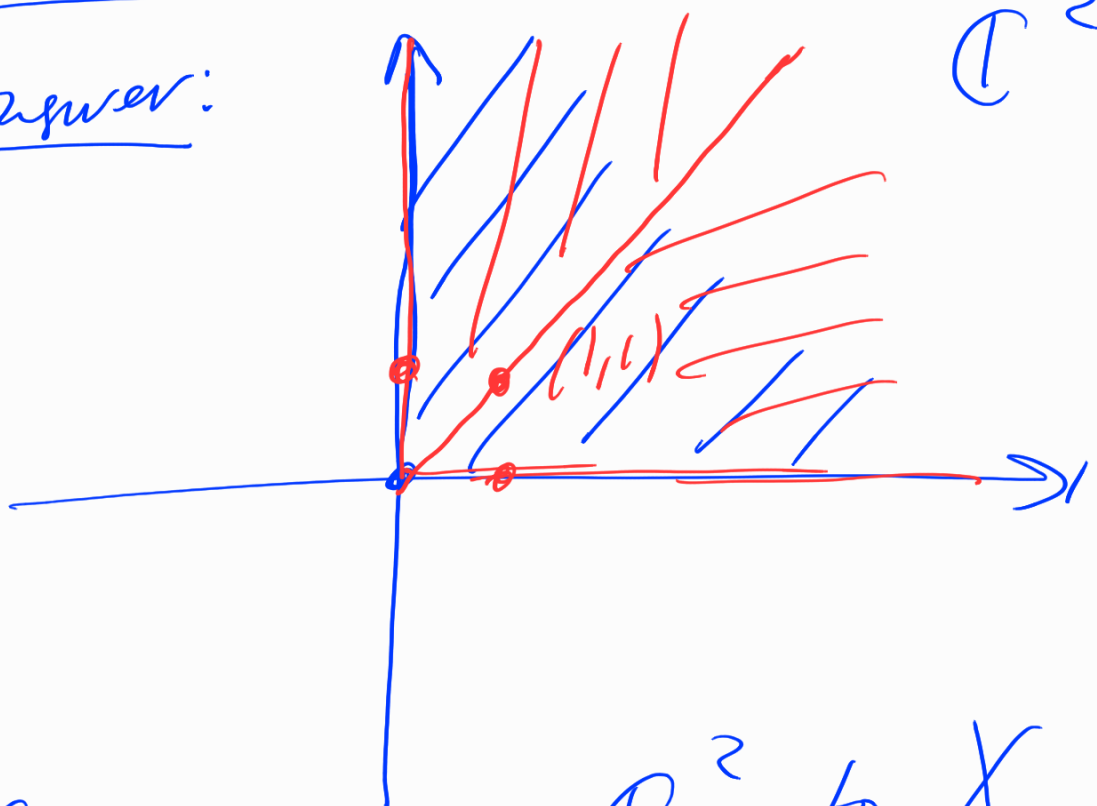
$$z = \frac{x}{y}$$

$\mathbb{P}^2$ $\mathcal{O}(X, Y)$

X $\mathcal{O}(X, Y)$

What is this really

Answer:



Going from $\mathbb{P}^2$ to X
corresponds to a
subdivision of a cone.

