SUPPLEMENT ON SETS AND FUNCTIONS

1. Logic

A (logical) statement is something that can be true or false. For example, "All rocks are red" is a statement, but it happens to be false. "Some rocks are red" is a different statement and it happens to be true. "Many rocks are red" is a bit of a problem for logic, because I don't know exactly what "many" means; it could mean many (sic) things such as "hundreds of rocks are red" (true, I'm sure) or "40% of all rocks are red" (false on the Earth, possibly true on Mars), etc. "A cube" is not a statement since it's meaningless to say it is true or false.

Suppose P and Q are statements. We can combine them into compound statements, such as:

- A. "P and Q" is the statement that both P and Q are true.
- B. "P or Q" is the statement that P or Q or both are true. Note that "or" does not mean only one is true; it could be one or both. That is the meaning in logic. (In ordinary speech "or" is ambiguous: it could mean only one is true, or it could mean one or both are true. Logic is strict about precise meanings.)
- C. "If P, then Q" or "P implies Q" means that if we know P is true, then we can be sure Q is true. If P is not true, we can't be sure about Q unless we have other information.
- D. "Not P" means P is false. (We call "Not P" the negation of P.)

2. Sets

I assume everyone knows what a set is. Here are some reminders and notations. I use capital letters W, X, Y, Z for sets and lower-case letters w, x, y, z for elements of sets.

Set definition: The set of all objects that have a certain property is written

 $\{x : x \text{ has the property}\}.$

We read this as follows: "The set of all x such that x has the property". You put in the property you want. For example, if the property is being a solution to Ax = b, we would write $\{x : x \text{ is a solution of } Ax = b\}$, but a simpler way is

$$\{x : Ax = b\}.$$

Usually, to be clear, we want to say that x must be in some big set, say U; then we write $\{x \in U : x \text{ has the property}\}$. For example,

$$\{x \in \mathbb{R}^n : Ax = b\}.$$

Intersection: $X \cap Y = \{x : x \in X \text{ and } x \in Y\}$. **Union :** $X \cup Y = \{x : x \in X \text{ or } x \in Y\}$. (Remember what "or" means in logic.)

3. Functions

A function is a rule for taking an element of one set, say X, and producing an element of another set, say Y (but it could be the same set!). We call X the *domain* of the function, Y the *codomain*, and we give a name to the function so we can talk about it, say f (surprise?). Then we say f is a function from X to Y and we write $f : X \to Y$. In calculus you see functions like $y = x^2$, where the function is $f(x) = x^2$, the domain is \mathbb{R} , and the codomain is also \mathbb{R} . Summary about functions:

- **Function:** $f: X \to Y$ is any rule that, given an element $x \in X$, gives back a unique element $y \in Y$. We write y = f(x). (Usually the rule is a formula.)
- **Domain:** X is the domain of this function. It is where the inputs are.

Codomain: Y is the codomain of this function. It is where the values are.

The domain and codomain may be the same set or different sets.

Range or Image: Range (f) is the set of all the values that f(x) can possibly take on, if you give it every element of the domain. Formally,

Range
$$(f) = \{y : \text{there is an } x \in X \text{ such that } y = f(x)\}$$

= $\{f(x) : x \in X\}.$

The range may be the whole codomain, or it may be only a proper subset.

4. Functions in linear Algebra

Here is a function we use often in linear algebra. Let A be an $m \times n$ matrix. Then $f(\mathbf{x}) = A\mathbf{x}$ is a function defined for all $\mathbf{x} \in \mathbb{R}^n$; we write $f : \mathbb{R}^n \to \mathbb{R}^m$. That is, the domain is \mathbb{R}^n ; the function takes any element of \mathbb{R}^n and gives us an element of \mathbb{R}^m (the codomain).

Example. We do not expect to get every single element of \mathbb{R}^m (the codomain) as a value of the function (i.e., as a value of $A\mathbf{x}$). For example, let O be the zero matrix (all 0's); then $A\mathbf{x} = \mathbf{0} \in \mathbb{R}^m$ for every \mathbf{x} , which means the function defined by $f(\mathbf{x}) = O\mathbf{x}$ misses almost all vectors in the codomain.

Returning to the general picture with $f(\mathbf{x}) = A\mathbf{x}$ where A is an arbitrary $m \times n$ matrix: There is a name for the set of vectors in the domain that we do get: it is the *range* or *image* of the function and its definition is

Range $(f) = \{ \mathbf{y} \in \mathbb{R}^m : \text{there is a vector } \mathbf{x} \in \mathbb{R}^n \text{ such that } \mathbf{y} = A\mathbf{x} \}.$

A simpler way to write this is

Range
$$(f) = \{A\mathbf{x} : \mathbf{x} \in \mathbb{R}^n\}.$$

Example. For the function f given by $f(\mathbf{x}) = O\mathbf{x}$, the only value is the zero vector, $\mathbf{0}$. Then Range $(f) = \{\mathbf{0}\}$, which is a small subset of the codomain, \mathbb{R}^m .