

Do for discussion Mon., 5/1

An ordered basis for P_n is $X_n = (x^0, x, x^2, \dots, x^n)$. An ordered basis for \mathbb{R}^m is $E_m = (\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_m)$.

Another ordered basis for \mathbf{P}_2 is $B = (x^2 + 1, x + 1, 1)$. One ordered basis for \mathbb{R}^3 is $C = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ (the same as E_3). Another ordered basis for \mathbb{R}^3 is $D = (\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3)$ where

$$\mathbf{w}_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \quad \mathbf{w}_2 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \quad \mathbf{w}_3 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}.$$

Still another ordered basis is $Y = (\mathbf{y}_1, \mathbf{y}_2, \mathbf{y}_3)$ where

$$\mathbf{y}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{y}_2 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \quad \mathbf{y}_3 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

1. Define a function $L : \mathbf{P}_2 \rightarrow \mathbb{R}^3$ by

$$L(a_0x^0 + a_1x + a_2x^2) = \begin{bmatrix} a_1 + a_0 \\ a_1 + a_2 \\ a_0 + a_2 \end{bmatrix}.$$

- (a) Prove that L is a linear transformation.
 (b) Now assume that L is a linear transformation. Prove that L is an isomorphism by finding the inverse function $L^{-1} : \mathbb{R}^3 \rightarrow \mathbf{P}_2$.
 (c) Find

$$p_1(x) = L^{-1}(\mathbf{e}_1), \quad p_2(x) = L^{-1}(\mathbf{e}_2), \quad p_3(x) = L^{-1}(\mathbf{e}_3),$$

and prove that $\{p_1(x), p_2(x), p_3(x)\}$ is a basis for \mathbf{P}_2 .

2. (a) Find the matrix ${}_C L_B$ of L with respect to ordered bases B and C .
 (b) Find the matrix ${}_D L_B$ of L with respect to B and D .
 (c) Is L an isomorphism? (Solve by using part (a) or (b), and not the method of the preceding problem.)

3. A linear transformation $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is defined by

$$F(\mathbf{w}_1) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad F(\mathbf{w}_2) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad F(\mathbf{w}_3) = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

- (a) Find the matrix ${}_C F_D$.
 (b) Find the matrix ${}_D (F^{-1})_C$. Multiply by ${}_C F_D$: what do you get?
 (c) Find the matrix ${}_C F_C$ and compare with (a).
 (d) Find ${}_C (F^{-1})_C$ and compare with (b). Multiply by ${}_C F_C$: what do you get? What does that say about the relationship between these two matrices?
 (e) Find ${}_D F_C$ and compare with (a), (b), and (c).

4. A linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ is defined by having matrix

$${}_{E_2}T_D = \begin{bmatrix} 2 & 0 & -1 \\ 0 & 3 & 1 \end{bmatrix}.$$

Find a formula for

$$T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right).$$

5. A linear transformation $G : V \rightarrow W$ has the matrix

$$\begin{bmatrix} 4 & 8 & 0 & -1 \\ 0 & 0 & 3 & 1 \\ -2 & 0 & -3 & 1 \end{bmatrix}$$

with respect to bases X and Y .

- What are the dimensions of V and W ?
- If V is a P_n and W is an \mathbb{R}^m , what are n and m ?
- Use the ordered bases $X = X_n$ for \mathbf{P}_n and $Y = E_m$ for \mathbb{R}^m . With your values for n and m from part (b), write out X and Y completely.
- Find a direct formula for G of the form:

$$G(a_0 + a_1x + \cdots + a_nx^n) = (\text{fill in the correct matrix here}).$$

6. Here we just have one vector space, \mathbb{R}^3 , but different bases.

- Find the basis-change matrix ${}_Y I_D$ that changes coordinates with respect to D in \mathbb{R}^3 to coordinates with respect to Y .
- Find the basis-change matrix ${}_D I_Y$ that changes from coordinates with respect to Y to coordinates with respect to D . Multiply the answers to (a) and (b): what do you get? Is that a coincidence or will it always happen that way?
- Find the basis-change matrix ${}_C I_D$ that changes coordinates with respect to D in \mathbb{R}^3 to coordinates with respect to C .
- Find the basis-change matrix ${}_D I_C$ that changes from coordinates with respect to C to coordinates with respect to D . Multiply the answers to (c) and (d): what do you get? Does this suggest an easier way to find the answer to part (d)?