

Exam 2 (§ 2.1 – 2.3, 4.1 – 4.6)

Math 313-04

Dan Rossi

Fall 2017

Student's Name (please print): _____

By signing my name below, I agree that I am following all rules and regulations set forth by the Code of Academic Integrity. Furthermore, I agree that I am following all rules set by my instructor and by the course policy for this exam.

Signature: _____

Date: _____

Use correct notation and terminology, and be sure to **justify your answers** when required. The points for each part will be awarded holistically, with attention paid both to correctness and clear explanations. Unless otherwise noted, each part within a problem is worth an equal number of points.

1. [12 points] Complete the sentences below to precisely define the terms in bold.

(a) A set of vectors $\{v_1, \dots, v_n\}$ in a vector space V is a **basis** of V if ...

(b) An $n \times n$ matrix A is called **invertible** if ...

2. [12 points] Let A be a 2×2 invertible matrix and assume that $A^{-1} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$.

(a) Solve the equation $A\vec{x} = \begin{pmatrix} 2 \\ 4 \end{pmatrix}$.

(b) Find A .

(c) Find $(A^T)^{-1}$.

3. [16 points] Determine if the following are possible or impossible. If possible, give a *specific* example. If impossible, explain why.

(a) An $n \times n$ matrix A such that $\text{Col}(A) \neq \mathbb{R}^n$ and such that the equation $A\vec{x} = \vec{v}$ has a unique solution, for some \vec{v} in \mathbb{R}^n .

(b) A basis for \mathbb{P}_2 which does not contain *any* of the polynomials $1, x,$ or x^2 .

4. [20 points] In each part, decide if W is a subspace of V . Justify your answer to part (e) **only**.

(a) (3 points) $W = \mathbb{R}^2$, $V = \mathbb{R}^3$.

(b) (3 points) $W = \left\{ \begin{pmatrix} w \\ x \\ y \\ z \end{pmatrix} : \begin{array}{l} x + y + z = 0 \\ w + x = y \\ w - y + 2z = x \\ w, x, y, z \text{ are real numbers} \end{array} \right\}, V = \mathbb{R}^4.$

(c) (3 points) W is the set of all 3×3 *invertible* matrices, $V = M_{3 \times 3}$.

(d) (3 points) W is the set of all polynomials $p(x)$ in \mathbb{P}_2 with the property that $p(1) = 0$, $V = \mathbb{P}_2$.

(e) (8 points) $W = \left\{ \begin{pmatrix} a & a \\ b & a + b \end{pmatrix} : a, b \text{ are real numbers} \right\}, V = M_{2 \times 2}.$

5. [14 points] A square matrix A is called **skew-symmetric** if $A^T = -A$. The set V of all 3×3 skew-symmetric matrices is a subspace of $M_{3 \times 3}$ with dimension 3 (you do **not** need to show this).

(a) (8 points) Find a basis for V , and prove that it is a basis.

(b) (6 points) Find the coordinate vector of $A = \begin{pmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -3 & 0 \end{pmatrix}$, relative to the basis you found in part (a).

6. [14 points] If $A = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 4 & 3 & 2 & 1 \\ 1 & 3 & 2 & 4 \end{pmatrix}$ then $\text{rref}(A) = \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{pmatrix}$ (you do **not** need to show this).

Find bases for $\text{Nul}(A)$ and $\text{Col}(A)$. You do not need to prove that they are bases. (Make sure that you indicate which basis is which!)

7. [12 points] In this problem you will critique an answer to a linear algebra problem given by Janey Student (Johnny's sister). **Note:** the reduced echelon form Janey found is correct.

Problem: Let

$$\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \text{ and } \vec{v}_3 = \begin{pmatrix} 1 \\ -1 \\ -1 \\ 1 \end{pmatrix}.$$

Is it possible to find a vector \vec{v}_4 so that $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$ is a basis for \mathbb{R}^4 ?

Janey Student's Answer: Yes, it is possible. We know that $\dim \mathbb{R}^4 = 4$, so a basis for \mathbb{R}^4 must contain 4 vectors. Therefore, if we find a vector \vec{v}_4 such that \vec{v}_4 is not in $\text{Span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$, then $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$ is a basis for \mathbb{R}^4 .

Let $\vec{v}_4 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$. The equation

$$a\vec{v}_1 + b\vec{v}_2 + c\vec{v}_3 = \vec{v}_4$$

is inconsistent. We know this because

$$\text{rref}(\vec{v}_1 \quad \vec{v}_2 \quad \vec{v}_3 \quad | \quad \vec{v}_4) = \begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

has the row $(0 \ 0 \ 0 \ 1)$. This means that \vec{v}_4 is not in $\text{Span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ and therefore $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$ is a basis for \mathbb{R}^4 .

Is Janey's answer correct? If it is, then draw a picture of Janey in the space below. If not, then find the error in her argument and indicate how you would correct it.