

Exam 2 Practice Questions Suggested by Quincy Loney

1. Suppose A is a 4×3 matrix and \mathbf{b} is a vector in \mathbb{R}^4 with the property that $A\mathbf{x} = \mathbf{b}$ has a unique solution. What can you say about the reduced echelon form of A ?

Solution: The RREF for A must have a pivot in the first 3 rows followed by a zero row. If there were less than 3 pivots, there would be infinitely many solutions. There is no possibility for more than 3 pivots as there are only 3 columns.

2. Let A be a 2×5 matrix with two pivots.
- Does the homogeneous equation $A\mathbf{x} = \mathbf{0}$ have a non-trivial solution?
 - Does the equation $A\mathbf{x} = \mathbf{b}$ have at least one solution for every possible \mathbf{b} ?

Solution:

- Yes. The matrix A has 5 columns and 2 pivots. Hence there are 3 free variables. (Note that one free variable is sufficient for an affirmative answer.)
- Yes. The matrix $[A|\mathbf{b}]$ has 2 rows and 2 pivots. Both pivots occur as pivots for A . There is no way to obtain a pivot in the augmented row.

3. For the given matrices, find a nonzero vector in $\text{Nul}(A)$ and a nonzero vector in $\text{Col}(A)$.

(a)
$$\begin{bmatrix} 2 & -4 \\ -1 & 2 \\ -3 & 6 \\ 1 & -2 \end{bmatrix}$$

(b)
$$\begin{bmatrix} 2 & -1 & -3 & 1 \\ -4 & 2 & 6 & -2 \end{bmatrix}$$

Solution:

The null space of a matrix A is the set of all solutions of the homogeneous equation $A\mathbf{x} = \mathbf{0}$.

The column space of a matrix A is the set of all linear combinations of the columns of A .

- (a) Row reduce the augmented matrix to write the basic variables in terms of the free variables.
$$\left[\begin{array}{cc|c} 2 & -4 & 0 \\ -1 & 2 & 0 \\ -3 & 6 & 0 \\ 1 & -2 & 0 \end{array} \right] \sim$$

$$\left[\begin{array}{cc|c} 1 & -2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right], \text{ so } x_2 \text{ is free and } x_1 = 2x_2. \text{ Choose any non-zero value for } x_2, \text{ and write } \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}.$$

For example $\mathbf{x} = \begin{bmatrix} \frac{\pi}{2} \\ \frac{\pi}{4} \end{bmatrix}$. (We can always check that $A\mathbf{x} = \mathbf{0}$.)

Choose any column of A , or non-zero linear combination of the columns to answer the second part of

the question. For example
$$\begin{bmatrix} -e \\ \frac{e}{2} \\ \frac{3e}{2} \\ -\frac{e}{2} \end{bmatrix}.$$

$$(b) \left[\begin{array}{cccc|c} 2 & -1 & -3 & 1 & 0 \\ -4 & 2 & 6 & -2 & 0 \end{array} \right] \sim \left[\begin{array}{cccc|c} 2 & -1 & -3 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right], \text{ so that } x_2, x_3, x_4 \text{ are free and}$$

$$x_1 = 0.5x_2 + 1.5x_3 - 0.5x_4. \text{ One example is } x_2 = 2, x_3 = 0 = x_4 \text{ so that } \mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix}.$$

The first column is sufficient, $\begin{bmatrix} 2 \\ 4 \end{bmatrix}$.

4. Let A be the matrix $\begin{bmatrix} 1 & -2 & -1 \\ 4 & -2 & 2 \\ -7 & 1 & -6 \end{bmatrix}$ and let $\mathbf{w} = \begin{bmatrix} 2 \\ 2 \\ -2 \end{bmatrix}$ be a vector in \mathbb{R}^3 .

(a) Determine if \mathbf{w} is in $\text{Nul}(A)$.

(b) Determine if \mathbf{w} is in $\text{Col}(A)$.

Solution:

(a) The vector \mathbf{w} is in $\text{Nul}(A)$ because $A\mathbf{w} = \mathbf{0}$.

$$\begin{bmatrix} 1 & -2 & -1 \\ 4 & -2 & 2 \\ -7 & 1 & -6 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ -2 \end{bmatrix} = \begin{bmatrix} 2 - 4 + 2 \\ 8 - 4 - 4 \\ -14 + 2 + 12 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

(b) The vector \mathbf{w} is not in $\text{Col}(A)$ because the system $A\mathbf{x} = \mathbf{w}$ is inconsistent.

$$\left[\begin{array}{ccc|c} 1 & -2 & -1 & 2 \\ 4 & -2 & 2 & 2 \\ -7 & 1 & -6 & -2 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & -2 & -1 & 2 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & -1 \end{array} \right].$$

5.

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -4 \\ 2 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -3 \\ 12 \\ -6 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 5 \\ 6 \\ h \end{bmatrix}$$

(a) For what values of h is \mathbf{v}_3 in $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$?

(b) For what values of h is the set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ linearly dependent?

Solution:

(a) One way to solve this question would be to row reduce the augmented matrix

$$\left[\begin{array}{ccc|c} \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & -3 & 5 & 5 \\ -4 & 12 & 6 & 6 \\ 2 & -6 & h & h \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & -3 & 5 & 5 \\ 0 & 0 & 0 & 26 \\ 0 & 0 & h-10 & h-10 \end{array} \right].$$

Since there is a pivot in the augmented column, the system of equations represented by this matrix is inconsistent. Therefore \mathbf{v}_3 can not be written as a linear combination of \mathbf{v}_1 and \mathbf{v}_2 and is not in $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

Another valid solution is to notice that \mathbf{v}_2 is a scalar multiple of \mathbf{v}_1 , so they lie on the same line. It is impossible for \mathbf{v}_3 to be on this line since both of its first two components are positive. Hence $\mathbf{v}_3 \notin \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

- (b) This set is dependent because $\mathbf{v}_2 = -3\mathbf{v}_1$. Adding a vector to a dependent set, namely adding \mathbf{v}_3 to $\{\mathbf{v}_1, \mathbf{v}_2\}$ results in a dependent set. A choice for a dependence relation could be $3\mathbf{v}_1 + 1\mathbf{v}_2 + 0\mathbf{v}_3 = \mathbf{0}$. Since this set is dependent regardless of the inclusion of \mathbf{v}_3 , it will be dependent regardless of the choice of h . Therefore the set is dependent for all $h \in \mathbb{R}$.

6. Let $A = \begin{bmatrix} 1 & -2 & -1 \\ 4 & -2 & 2 \\ -7 & 1 & -6 \end{bmatrix}$.

- (a) Find a basis for $\text{Nul}(A)$
 (b) Find a basis for $\text{Col}(A)$

Solution:

- (a) Find the general solution to the homogeneous system $A\mathbf{x} = \mathbf{0}$.

$$\left[\begin{array}{ccc|c} 1 & -2 & -1 & 0 \\ 4 & -2 & 2 & 0 \\ -7 & 1 & -6 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]. \text{ The parametric form of the general solution is}$$

$$\mathbf{x} = s \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}, \text{ so a basis for } \text{Nul}(A) \text{ is } \mathcal{B} = \left\{ \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \right\}.$$

- (b) The pivots for A occur in the first two columns, therefore the first two column vectors form a basis for

$$\text{Col}(A), \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 4 \\ -7 \end{bmatrix}, \begin{bmatrix} -2 \\ -2 \\ 1 \end{bmatrix} \right\}.$$

7. Let $S = \{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ be a set of k vectors in \mathbb{R}^n . Explain why S cannot be a basis for \mathbb{R}^n

- (a) When $k < n$.
 (b) When $k > n$.

Solution:

- (a) When $k < n$, the matrix $A = [\mathbf{v}_1 \cdots \mathbf{v}_k]$ has fewer columns than rows. Thus there can not be a pivot in every row. This means that there is at least one zero row in $\text{RREF}(A)$. Augmenting A to solve the system $A\mathbf{x} = \mathbf{b}$, we can now find elements in \mathbb{R}^n which are not in the span of S . So, S is not a basis of \mathbb{R}^n .

- (b) When $k > n$ the matrix $A = [\mathbf{v}_1 \cdots \mathbf{v}_k]$ has fewer rows than columns. Thus there can not be a pivot in every column. This means that there is at least one column which is dependent on the columns preceding it. Since S is not a linearly independent set, it is not a basis of \mathbb{R}^n .

8. Find the vector \mathbf{x} determined by the coordinate vector $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} -2 \\ 1 \\ -1 \end{bmatrix}$ and the basis $\mathcal{B} = \left\{ \begin{bmatrix} 3 \\ 4 \\ -5 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \\ 2 \end{bmatrix} \right\}$.

Solution: Make sure that the weight c_i corresponds to ordered basis vector \mathbf{b}_i for each $1 \leq i \leq 3$.

$$\mathbf{x} = -2 \begin{bmatrix} 3 \\ 4 \\ -5 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix} - 1 \begin{bmatrix} 4 \\ -2 \\ 2 \end{bmatrix} = \begin{bmatrix} -8 \\ -6 \\ 7 \end{bmatrix}.$$

Note that the calculation above is merely the product of the change-of-basis matrix $P_{\mathcal{B}}$ and the coordinate vector $[\mathbf{x}]_{\mathcal{B}}$. Symbolically we just found $\mathbf{x} = P_{\mathcal{B}}[\mathbf{x}]_{\mathcal{B}}$.

9. Find the coordinate vector $[\mathbf{x}]_{\mathcal{B}}$ of $\mathbf{x} = \begin{bmatrix} 0 \\ 3 \\ -2 \end{bmatrix}$ relative to the basis $\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ 8 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix} \right\}$.

Solution: Using the notation from the previous question, $\mathbf{x} = P_{\mathcal{B}}[\mathbf{x}]_{\mathcal{B}}$.

To solve for $[\mathbf{x}]_{\mathcal{B}}$, treat this matrix equation exactly like any other matrix equation $A\mathbf{x} = \mathbf{b}$. Augment $P_{\mathcal{B}}$ with

$$\mathbf{x} \text{ and row reduce. } \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 1 & -3 & -1 & 3 \\ 3 & 8 & 3 & -2 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{array} \right]. \text{ Therefore } [\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}.$$

10. Show that the polynomials $1, 1-t, 2-4t+t^2, 6-18t+9t^2-t^3$ form a basis of \mathbb{P}_3 and find the coordinate vector $[\mathbf{x}]_{\mathcal{B}}$ of $17-27t+6t^2$ relative to this basis.

Solution: Note that if the four polynomials are linearly independent then they form a basis since $\dim \mathbb{P}_3 = 4$. Even though it may be easy to see that this particular set of polynomials is independent because each is of a different degree, we should practice using the techniques of this chapter.

We can express each of the polynomials as coordinate vectors relative to the standard basis of $\mathbb{P}_3; \{1, t, t^2, t^3\}$.

$$\text{Let } \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ -4 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 6 \\ -18 \\ 9 \\ -1 \end{bmatrix} \right\} \text{ which is an ordered list of the coordinate vectors. The change-}$$

of-basis matrix $P_{\mathcal{B}} = \begin{bmatrix} 1 & 1 & 2 & 6 \\ 0 & -1 & -4 & -18 \\ 0 & 0 & 1 & 9 \\ 0 & 0 & 0 & -1 \end{bmatrix}$ with columns from \mathcal{B} , has 4 pivots, so the columns are independent.

Write $17-27t+6t^2$ as the column vector $\begin{bmatrix} 17 \\ -27 \\ 6 \\ 0 \end{bmatrix}$ with respect to the standard basis, and then solve the

appropriate matrix equation (of the form $A\mathbf{x} = \mathbf{b}$).

$$[P_{\mathcal{B}}|\mathbf{b}] = \left[\begin{array}{cccc|c} 1 & 1 & 2 & 6 & 17 \\ 0 & -1 & -4 & -18 & -27 \\ 0 & 0 & 1 & 9 & 6 \\ 0 & 0 & 0 & -1 & 0 \end{array} \right] \sim \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 & 3 \\ 0 & 0 & 1 & 0 & 6 \\ 0 & 0 & 0 & 1 & 0 \end{array} \right] \text{ which means}$$

that $17-27t+6t^2 = 2(1) + 3(1-t) + 6(2-4t+t^2) + 0(6-18t+9t^2-t^3)$.

11. Let V be a finite dimensional vector space. True-False-Why

- (a) If there is a spanning set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ of vectors in V , then $\dim V \leq p$.
- (b) If there is a linearly independent set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ of vectors in V , then $\dim V \geq p$.
- (c) If there is a linearly dependent set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ of vectors in V , then $\dim V \leq p$.
- (d) If there is a linearly dependent set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ of vectors in V , then $\dim V \geq p$.

Solution:

- (a) True because a spanning set can always be pared down to a basis. If it is already an independent set, then $\dim V = p$.
- (b) True because an independent set can be expanded to a basis. If it is already a spanning set, then $\dim V = p$.
- (c) False. Consider \mathbb{R}^2 and $\{\mathbf{0}\}$. The set is dependent and has one element, yet $\dim \mathbb{R}^2 = 2$.
- (d) False. Consider \mathbb{R}^2 and $\{e_1, e_2, \mathbf{0}\}$. The set is dependent, and has 3 elements. yet $\dim \mathbb{R}^2 = 2$.

12. Let $M_{2 \times 2}$ be the vector space of all 2×2 matrices. Define $T : M_{2 \times 2} \rightarrow \mathbb{R}^3$ by $T \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = \begin{bmatrix} 2a + 3b - 5c + 2d \\ a + b - c - d \\ 3a + 2b - 7d \end{bmatrix}$.

- (a) Describe the kernel of T and a find basis for $\text{Ker}(T)$.
- (b) Is T one-to-one?
- (c) Find a basis for the range of T .
- (d) Is T onto?

Solution:

(a) $\text{Ker}(T)$ is the set of all 2×2 matrices which are mapped to $\mathbf{0} \in \mathbb{R}^3$, i.e. $\begin{bmatrix} 2a + 3b - 5c + 2d \\ a + b - c - d \\ 3a + 2b - 7d \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$.

Solve the system of equations given by the coordinates by row reduction.

$$\left[\begin{array}{cccc|c} 2 & 3 & -5 & 2 & 0 \\ 1 & 1 & -1 & -1 & 0 \\ 3 & 2 & 0 & -7 & 0 \end{array} \right] \sim \left[\begin{array}{cccc|c} 1 & 0 & 2 & -5 & 0 \\ 0 & 1 & -3 & 4 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \Rightarrow \begin{array}{l} a = -2r + 5s \\ b = 3r - 4s \\ c = r \\ d = s \end{array} \text{ for free variables } r \text{ and } s.$$

Thus $\text{Ker}(T) = \left\{ \begin{bmatrix} -2r + 5s & 3r - 4s \\ r & s \end{bmatrix} \in M_{2 \times 2} \mid r, s \in \mathbb{R} \right\}$.

A possible basis for $\text{Ker}(T)$ can be $\left\{ \begin{bmatrix} -2 & 3 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 5 & -4 \\ 0 & 1 \end{bmatrix} \right\}$.

(b) This map is not one-to-one because it has a non-trivial kernel. In particular both basis vectors found above are mapped to $\mathbf{0} \in \mathbb{R}^3$.

(c) The range of T is the set of all vectors in \mathbb{R}^3 that are outputs of the function T , i.e. vectors of the form $\begin{bmatrix} 2a + 3b - 5c + 2d \\ a + b - c - d \\ 3a + 2b - 7d \end{bmatrix}$, which are spanned by $\left\{ \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -5 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ -7 \end{bmatrix} \right\}$. These are the columns of the coefficient matrix that was row reduced in part (a).

Using the pivot columns we can write the basis $\left\{ \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} \right\}$.

(d) Since the dimension of the range is 2, the range of T can not be all of \mathbb{R}^3 , therefore this map is not onto.

13. Let $M_{2 \times 2}$ be the vector space of all 2×2 matrices. Define $T : M_{2 \times 2} \rightarrow M_{2 \times 2}$ by $T(A) = A + A^T$.

- Show that T is a linear transformation.
- Let B be in $M_{2 \times 2}$ such that $B = B^T$. Find an A such that $T(A) = B$.
- Show that the range of T is the set of B such that $B = B^T$.
- Describe the kernel of T .

Solution:

$$(a) \quad T \left(\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \right) = T \left(\begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} \\ a_{21} + b_{21} & a_{22} + b_{22} \end{bmatrix} \right) =$$

$$\begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} \\ a_{21} + b_{21} & a_{22} + b_{22} \end{bmatrix} + \begin{bmatrix} a_{11} + b_{11} & a_{21} + b_{21} \\ a_{12} + b_{12} & a_{22} + b_{22} \end{bmatrix} = \dots = T \left(\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \right) + T \left(\begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \right).$$

The scalar multiple portion works as expected as well.

(b) If $B = B^T$, then $T(B) = B + B^T = B + B = 2B$. Choose $A = 0.5B$ so that $T(A) = 0.5T(B) = (0.5)(2)B = B$.

(c) Let B be in the range of T . Then $B = T(A)$ for some $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ in $M_{2 \times 2}$. We can calculate

$$B = T \left(\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \right) = \begin{bmatrix} a_{11} + a_{11} & a_{12} + a_{21} \\ a_{12} + a_{21} & a_{22} + a_{22} \end{bmatrix}. \text{ Now it is easy to see that } B^T \text{ is equal to } B.$$

(d) $T \left(\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \right) = \begin{bmatrix} a_{11} + a_{11} & a_{12} + a_{21} \\ a_{12} + a_{21} & a_{22} + a_{22} \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ means, $a_{11} = 0 = a_{22}$ and $a_{12} = -a_{21}$. So the kernel is the set of matrices of the form $\begin{bmatrix} 0 & a_{12} \\ -a_{12} & 0 \end{bmatrix}$.

14. Let A be an $n \times n$ matrix whose columns are linearly independent. Explain why the columns of A^2 span \mathbb{R}^n .

Solution: Since A is a square matrix with linearly independent columns, A is row equivalent to I_n and therefore invertible. Since $A^2 = AA$ is a product of invertible matrices, it too is invertible and is row equivalent to I_n . Therefore the columns of A^2 span \mathbb{R}^n .

15. Suppose a 6×8 matrix has rank 5.

- Find $\dim \text{Nul}(A)$
- Find $\dim \text{Row}(A)$
- Find $\text{rank } A^T$

Solution:

- (a) The matrix has 8 columns and 5 of them are pivot columns, so 3 of them are non-pivot columns.
- (b) The rank is also the dimension of the row space.
- (c) The column space of a matrix is the same as the row space of its transpose.

16. Suppose a 6×8 matrix has two pivot columns.

- (a) Find $\dim \text{Nul}(A)$
- (b) Is $\text{Col}(A) = \mathbb{R}^2$?

Solution:

- (a) There are 8 columns so 6 of them are non-pivot columns.
- (b) The column space is a subspace of \mathbb{R}^6 which is isomorphic to \mathbb{R}^2 ... not equal to.