

1. (10 Pts) If  $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 6 \end{bmatrix}$  then the reduced row echelon form of  $A$  is  $\begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ .

(a) (4 Pts) Find a basis for  $\text{Col}(A)$ .

**Solution:** Since  $A$  row reduced to the matrix above with pivot columns 1 and 2, a basis for  $\text{Col}(A)$  can be  $\{\text{Col}_1(A), \text{Col}_2(A)\}$ .

(b) (4 Pts) Find a basis for  $\text{Nul}(A)$ .

**Solution:** Since  $A$  row reduced to the matrix above, the solutions to  $AX = 0$  are

$$\text{Nul}(A) = \left\{ \begin{bmatrix} r + 2s \\ -2r - 3s \\ r \\ s \end{bmatrix} = r \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 2 \\ -3 \\ 0 \\ 1 \end{bmatrix} \in \mathbb{R}^4 \mid r, s \in \mathbb{R} \right\} \text{ so } \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ is}$$

a basis for  $\text{Nul}(A)$ .

(c) (2 Pts) Find the dimension of  $\text{Row}(A)$ .

**Solution:** Since there are 2 non-zero rows in the  $RREF(A)$ ,  $\dim(\text{Row}(A)) = 2$ .

2. (9 Pts) Let  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  be a set of  $k$  vectors in  $\mathbb{R}^n$ . Consider the following statements.

(A) The set  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  is linearly independent.

(B)  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  is linearly dependent.

(C)  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  spans  $\mathbb{R}^n$ .

(D)  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  does not span  $\mathbb{R}^n$ .

(E)  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  is a basis for  $\mathbb{R}^n$ .

(F)  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  is not a basis for  $\mathbb{R}^n$ .

In each part, determine which of the statements (A)–(F) *must* be true about  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ .

There may be more than one true statement. Choose all that apply. No justification required.

**Solutions:**

(a) (3 Pts)  $k < n$     D and F

(b) (3 Pts)  $k > n$     B and F

(c) (3 Pts)  $k \neq n$     F

3. (8 Pts) Answer each part. No justification required.

**Solutions:**

(a) (2 Pts) If  $T : \mathbb{R}^8 \rightarrow \mathbb{R}_2^3$  is a surjective linear transformation, then  $\dim \text{Ker}(T) = 2$

(b) (2 Pts) Can a linear map  $L : \mathbb{R}^6 \rightarrow \mathcal{P}_4(t)$  be injective? No

(c) (2 Pts) Select the word that makes the sentence true.

If  $w \notin \text{Span}(\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ , and the vectors  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  are linearly independent, then the set  $\{w, \mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  is *never* linearly dependent.

(d) (2 Pts) If none of the vectors  $\mathbf{v}_1, \mathbf{v}_2$ , and  $\mathbf{v}_3$  are scalar multiples of one another, is the set  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  *necessarily* linearly independent? No

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4. (8 Pts) Find the inverse of each matrix, or determine that it is not invertible.

**Solutions:**

(a) (4 Pts)  $\begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} -1 & 1 & 0 \\ 1 & 0 & -1 \\ 0 & 0 & 1 \end{bmatrix}$

(b) (4 Pts)  $\begin{bmatrix} -1 & 3 & 2 \\ 3 & -9 & 1 \\ 2 & -6 & 3 \end{bmatrix}$  row reduces to a matrix with a zero row, so it is not invertible.

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5. (10 Pts) Let  $W$  be the set of all  $n \times n$  symmetric matrices; that is,  $W = \{A \in \mathbb{R}_n^n : A = A^T\}$ .

a. (5 Pts) Show that  $W$  is a subspace of  $\mathbb{R}_n^n$ .

**Solution:**

For any  $A, B \in W$  we have  $A^T = A$  and  $B^T = B$  so  $(A + B)^T = A^T + B^T = A + B$  so  $A + B \in W$ .

For any  $A \in W$  and  $r \in \mathbb{R}$  we have  $(rA)^T = r(A^T) = rA$  so  $rA \in W$ .

Finally,  $(0_n^n)^T = 0_n^n$  so  $0_n^n \in W$ . So  $W$  is a **subspace** of  $\mathbb{R}_n^n$ .

b. (5 Pts) When  $n = 2$ , find a basis for  $W$ .

**Solution:**

When  $n = 2$ , a basis for  $W = \left\{ \begin{bmatrix} a & b \\ b & c \end{bmatrix} \mid a, b, c \in \mathbb{R} \right\}$  is  $\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ .

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6. (10 Pts) In  $\mathcal{P}_2(t)$ , let

$$p_1(t) = t^2 + 1, \quad p_2(t) = t^2 + t, \quad p_3(t) = t + 1.$$

(a) (4 Pts) Show that the set  $\mathcal{B} = \{p_1(t), p_2(t), p_3(t)\}$  is linearly independent.

**Solution:** We need to show that  $\sum_{i=1}^3 x_i p_i(t) = 0$  has only the trivial solution. It means  $(x_1 + x_2)t^2 + (x_2 + x_3)t + (x_1 + x_3) = 0$  so we get three equations in three variables, since each coefficient must be 0. Solving the system by row reduction or by hand gives the only solution is  $x_1 = x_2 = x_3 = 0$ .

(b) (2 Pts) Without further calculation explain why  $\{p_1(t), p_2(t), p_3(t)\}$  is a basis for  $\mathcal{P}_2(t)$ .

**Solution:**  $\dim(\mathcal{P}_2(t)) = 3$  so any three independent vectors in  $\mathcal{P}_2(t)$  form a basis of it.

(c) (4 Pts) If  $q(t) = t^2 + 2$ , find the coordinate vector  $[q(t)]_{\mathcal{B}}$ .

**Solution:** We need to solve  $\sum_{i=1}^3 x_i p_i(t) = q(t)$ , that is,

$$(x_1 + x_2)t^2 + (x_2 + x_3)t + (x_1 + x_3) = t^2 + 2$$

which gives the linear system:  $x_1 + x_2 = 1$ ,  $x_2 + x_3 = 0$ ,  $x_1 + x_3 = 2$ . Solve it by row reducing

$$\left[ \begin{array}{ccc|c} 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 2 \end{array} \right] \text{ to } \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 3/2 \\ 0 & 1 & 0 & -1/2 \\ 0 & 0 & 1 & 1/2 \end{array} \right] \text{ so } [q(t)]_{\mathcal{B}} = \begin{bmatrix} 3/2 \\ -1/2 \\ 1/2 \end{bmatrix}.$$

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7. (5 Pts) For what values of  $r$  is the set  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  linearly dependent? The vectors are

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ r \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} r \\ 3 \\ 3 \end{bmatrix}.$$

**Solution:** The set is dependent when  $r = 0$  or when  $r = 3$ . To see this, row reduce

$\begin{bmatrix} 1 & 1 & r \\ r & 1 & 3 \\ 0 & 1 & 3 \end{bmatrix}$  to  $\begin{bmatrix} 1 & 1 & r \\ r & 0 & 0 \\ 0 & 1 & 3 \end{bmatrix}$ . It has a zero row when  $r = 0$ . When  $r \neq 0$  it reduces further to  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & r \\ 0 & 0 & (3-r) \end{bmatrix}$ , which has rank 2 when  $r = 3$ , but has rank 3 otherwise.

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8. (5 Pts) Let

$$p_1(t) = 1 + 2t + 3t^2, \quad p_2(t) = 3 - t, \quad p_3(t) = 2 + 2t^2.$$

Then  $\mathcal{T} = \{p_1(t), p_2(t), p_3(t)\}$  is a basis of  $\mathcal{P}_2(t)$ . Suppose  $q(t) \in \mathcal{P}_2(t)$  has the following coordinates with respect to  $\mathcal{T}$ :  $[q(t)]_{\mathcal{T}} = \begin{bmatrix} -2 \\ 1 \\ -1 \end{bmatrix}$ . Find the polynomial  $q(t)$ .

**Solution:** From those coordinates with respect to  $\mathcal{T}$  we have that

$$q(t) = -2(1 + 2t + 3t^2) + 1(3 - t) - 1(2 + 2t^2) = -2 - 4t - 6t^2 + 3 - t - 2 - 2t^2 = -1 - 5t - 8t^2.$$

9. (10 Pts) Let

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\} \quad \text{and} \quad \mathcal{C} = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$$

be bases for  $\mathbb{R}^3$  and  $\mathbb{R}^2$ , respectively.

(a) (5 Pts) Let  $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  be the linear function defined by

$$L \left( \begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} 2x - y + 3z \\ x + 2y - 4z \end{bmatrix}.$$

Find the matrix for  $L$  relative to the bases  $\mathcal{B}$  and  $\mathcal{C}$ . That is, find  ${}_C L_{\mathcal{B}}$ .

**Solution:** First we find  $L(\mathcal{B})$ :  $L \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \end{bmatrix}$ ,  $L \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ -2 \end{bmatrix}$ ,  $L \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$ .

$$\text{Row reduce } \left[ \begin{array}{cc|cc} 1 & 1 & 4 & 2 & -1 \\ 1 & 2 & -1 & -2 & 2 \\ \hline & c & & L(\mathcal{B}) & \end{array} \right] \text{ to } \left[ \begin{array}{cc|cc} 1 & 0 & 9 & 6 & -4 \\ 0 & 1 & -5 & -4 & 3 \\ \hline & I_2 & & {}_C L_{\mathcal{B}} & \end{array} \right] \text{ so } {}_C L_{\mathcal{B}} = \begin{bmatrix} 9 & 6 & -4 \\ -5 & -4 & 3 \end{bmatrix}$$

(b) (5 Pts) If  $\mathcal{E} = \{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$  is the standard basis for  $\mathbb{R}^3$ , find  ${}_{\mathcal{B}} P_{\mathcal{E}}$  = the change of basis matrix from  $\mathcal{E}$  to  $\mathcal{B}$ .

$$\text{Solution: Row reduce } \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 \\ \hline & \mathcal{B} & & \mathcal{E} & & \end{array} \right] \text{ to } \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 & -1 \\ \hline & I_3 & & {}_{\mathcal{B}} P_{\mathcal{E}} & & \end{array} \right] \text{ so } {}_{\mathcal{B}} P_{\mathcal{E}} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 1 \\ 0 & 1 & -1 \end{bmatrix}.$$