

No books, no notes, no calculators. You must show work, unless the question is a true/false, multiple choice, or fill-in-the-blank question.

1. Fill in the blanks in the following definitions and statements of results from the textbook.

(a) (4 points) A linear transformation L from one vector space to another has two fundamental properties:

1. For all vectors u and v , $\underline{L(u + v) = L(u) + L(v)}$.
2. For all vectors w and all scalars c , $\underline{L(cw) = cL(w)}$.

Hint: The properties above are listed in Chapter 1 with the heading “The key to the whole class ...”.

(b) (6 points) A matrix is said to be in “reduced row echelon form” if the following conditions are met:

0. All zero rows are below all non-zero rows.
1. In each non-zero row, the leftmost non-zero entry, called a pivot, is 1.
2. The pivot of any given row is always strictly to the right of the pivot in the row above it.
3. The pivot is the only nonzero entry in its column.

(c) (4 points) Suppose $B = (v_1, v_2, \dots, v_n)$ is an ordered basis for a vector space V . The notation below defines a vector in V which is given by the equation:

$$\begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}_B = \underline{a_1v_1 + a_2v_2 + \cdots + a_nv_n}$$

(d) (3 points) The *Cauchy-Schwarz inequality* states that for any two vectors $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$, the absolute value of the dot product, $|\mathbf{u} \cdot \mathbf{v}| \leq \|\mathbf{u}\| \|\mathbf{v}\|$

(e) (3 points) Theorem 7.5.1 states that an $n \times n$ matrix M is invertible if and only if the system of n equations in n unknowns $M\mathbf{x} = \mathbf{0}$ has no solution except $\mathbf{x} = \mathbf{0}$.

2. (12 points) Let V be the vector space of polynomials of degree less than or equal to 2. Let B be the ordered basis $(x^2, x, 1)$ for V . Let $L: V \rightarrow V$ be the linear transformation $\frac{d}{dx}$.

Find ${}_B L_B$, that is, the matrix of L with respect to the basis B (used as both the input basis and output basis).

Solution: The matrix ${}_B L_B$ is, by definition (Chapter 7), the matrix whose columns are the coefficients in the expressions of the image vectors $(L(x^2), L(x), L(1))$ with respect to the vectors $(x^2, x, 1)$. We compute $L(x^2) = 2x = 0x^2 + 2 \cdot x + 0 \cdot 1$, so the entries in the first column of the matrix are, top to bottom, 0, 2, 0. The next column has entries 0, 0, 1 because $L(x) = 0 \cdot x^2 + 0 \cdot x + 1 \cdot 1$. The last column is all zeroes, because $L(1) = 0 \cdot x^2 + 0 \cdot x + 0 \cdot 1$. Thus we have

$${}_B L_B = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

3. (12 points) Let S and T be linear transformations from \mathbb{R}^2 to \mathbb{R}^2 defined by

$$S \left(\begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} -2 & -2 \\ -2 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \quad T \left(\begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} -3 & 0 \\ -3 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Find the matrix of the composition $T \circ S$ (with respect to the standard basis of \mathbb{R}^2), that is, the function that sends

$$\begin{bmatrix} x \\ y \end{bmatrix} \quad \text{to} \quad T \left(S \left(\begin{bmatrix} x \\ y \end{bmatrix} \right) \right)$$

Solution: The matrix of the composition is the product of the matrices, so the matrix of $T \circ S$ is

$$\begin{bmatrix} 6 & 6 \\ 8 & 7 \end{bmatrix} = \begin{bmatrix} -3 & 0 \\ -3 & -1 \end{bmatrix} \begin{bmatrix} -2 & -2 \\ -2 & -1 \end{bmatrix}$$

4. Let \mathbf{u} , \mathbf{v} , \mathbf{w} , \mathbf{x} be vectors such that

$$\mathbf{u} \cdot \mathbf{v} = 8, \quad \mathbf{u} \cdot \mathbf{w} = -7, \quad \mathbf{v} \cdot \mathbf{w} = 6, \quad \text{and} \quad -2\mathbf{u} + 6\mathbf{v} = \mathbf{x}.$$

(a) (3 points) Find the dot product $\mathbf{v} \cdot \mathbf{u}$.

$$\text{Solution: } \mathbf{v} \cdot \mathbf{u} = \mathbf{u} \cdot \mathbf{v} = 8.$$

(b) (7 points) Find the dot product $\mathbf{x} \cdot \mathbf{w}$.

$$\text{Solution: } \mathbf{x} \cdot \mathbf{w} = (-2\mathbf{u} + 6\mathbf{v}) \cdot \mathbf{w} = -2(\mathbf{u} \cdot \mathbf{w}) + 6(\mathbf{v} \cdot \mathbf{w}) = -2 \cdot (-7) + 6 \cdot 6 = 36 + 14 = 50.$$

5. (10 points) Give a geometric description of the following system of equations:

$$\begin{aligned} 15x + 9y - 15z &= -6 \\ 25x + 15y - 25z &= -10 \\ -35x - 21y + 35z &= 14 \end{aligned}$$

Hints: this was a homework question. A “geometric description” is something like “these equations represent two lines in the plane, which intersect at the origin.”

Solution: These three equations represent three planes in \mathbb{R}^3 . Row reducing this matrix leaves only one nonzero row, so all the planes are identical, and the intersection is that plane. This plane does *not* pass through the origin.

6. (10 points) Given the following LU factorization of the matrix M :

$$M = \begin{bmatrix} -2 & -3 & 1 \\ 6 & 5 & 1 \\ -6 & 3 & -8 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 3 & -3 & 1 \end{bmatrix} \begin{bmatrix} -2 & -3 & 1 \\ 0 & -4 & 4 \\ 0 & 0 & 1 \end{bmatrix} = LU$$

Use this factorization to solve the system of equations:

$$\begin{bmatrix} -2 & -3 & 1 \\ 6 & 5 & 1 \\ -6 & 3 & -8 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 10 \\ -30 \\ 29 \end{bmatrix}$$

Solution: First we introduce the notation:

$$X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \text{and} \quad V = \begin{bmatrix} 10 \\ -30 \\ 29 \end{bmatrix}$$

Now define $W = UX$, so that $MX = V$ becomes $LUX = V$, or $LW = V$.

We solve for W (forward substitution) and obtain

$$W = \begin{bmatrix} 10 \\ 0 \\ -1 \end{bmatrix}$$

Then solve for X in $UX = W$, and obtain

$$X = \begin{bmatrix} -4 \\ -1 \\ -1 \end{bmatrix}$$